



### Lecture Outline

- Introduction to queueing systems
- Conceptual representation of queueing systems
- Codes for queueing models
- Terminology and notation
- Little's Law and basic relationships

Reference: Chapter 4, pp. 182-193













## Strengths and Weaknesses of Queueing Theory

- Queueing models necessarily involve approximations and simplification of reality
- Results give a sense of order of magnitude, changes relative to a baseline, promising directions in which to move
- Closed-form results essentially limited to "steady state" conditions and derived primarily (but not solely) for birth-and-death systems and "phase" systems
- Some useful bounds for more general systems at steady state
- Numerical solutions increasingly viable for dynamic systems
- Huge number of important applications







#### Some Expected Values of Interest at Steady State

• Given:

 $\lambda$  = arrival rate

 $\mu$  = service rate per service channel

• Unknowns:

- \_ L = expected number of users in queueing system
- $L_q$  = expected number of users in queue
- \_ W = expected time in queueing system per user (W = E(w))
- $W_q = \text{expected waiting time in queue per user } (W_q = E(w_q))$
- 4 unknowns ⇒ We need 4 equations



## **Relationships among** *L*, *L*<sub>q</sub>, *W*, *W*<sub>q</sub> • Four unknowns: *L*, *W*, *L*<sub>q</sub>, *W*<sub>q</sub> • Need 4 equations. We have the following 3 equations: $-L = \lambda W$ (Little's law) $-L_q = \lambda W_q$ $-W = W_q + \frac{1}{\mu}$ • If we can find any one of the four expected values, we can determine the three others • The determination of *L* (or other) may be hard or easy depending on the type of queueing system at hand • $L = \sum_{n}^{\infty} nP_n$ (*P*<sub>n</sub> : probability that *n* customers are in the system)





# The differential equations that determine the state probabilities $P_n(t + \Delta t) = P_{n+1}(t) \cdot \mu_{n+1} \cdot \Delta t + P_{n-1}(t) \cdot \lambda_{n-1} \cdot \Delta t + P_n(t) \cdot [1 - (\mu_n + \lambda_n) \cdot \Delta t]$ After a simple manipulation: $\frac{dP_n(t)}{dt} = -(\lambda_n + \mu_n) \cdot P_n(t) + \lambda_{n-1} \cdot P_{n-1}(t) + \mu_{n+1} \cdot P_{n+1}(t) \quad (1)$ (1) applies when n = 1, 2, 3, ...; when n = 0, we have: $\frac{dP_0(t)}{dt} = -\lambda_0 \cdot P_0(t) + \mu_1 \cdot P_1(t) \quad (2)$ • The system of equations (1) and (2) is known as the Chapman-Kolmogorov equations for a birth-and-death system





