



# **Lecture Outline**

- **Introduction to queueing systems**
- **Conceptual representation of queueing systems**
- **Codes for queueing models**
- **Terminology and notation**
- **Little's Law and basic relationships**

*Reference: Chapter 4, pp. 182-193* 













## **Strengths and Weaknesses of Queueing Theory**

- **Queueing models necessarily involve approximations and simplification of reality**
- **Results give a sense of order of magnitude, changes relative to a baseline, promising directions in which to move**
- **Closed-form results essentially limited to "steady state" conditions and derived primarily (but not solely) for birth-and-death systems and "phase" systems**
- **Some useful bounds for more general systems at steady state**
- **Numerical solutions increasingly viable for dynamic systems**
- **Huge number of important applications**







#### **Some Expected Values of Interest at Steady State**

• *Given:* 

 $\lambda$  = arrival rate

 $\mu$  = service rate per service channel

• *Unknowns:* 

- \_ *L*  **= expected number of users in queueing system**
- \_ *Lq*  **= expected number of users in queue**
- \_ *W W* **= = expected time in queueing system per user (** *E***(***w***))**
- $M_q$  = expected waiting time in queue per user ( $W_q$  =  $E(w_a)$
- **4 unknowns** ⇒ **We need 4 equations**



## **Relationships among** *L***,** *Lq, W***,** *Wq*  • **Four unknowns:** *L***,** *W***,** *Lq***,** *Wq*  • **Need 4 equations. We have the following 3 equations:**   $L = \lambda W$  (Little's law)  $L_q = \lambda W_q$  $W = W_q + \frac{1}{\mu}$ • **If we can find any one of the four expected values, we can determine the three others**  • **The determination of** *L* **(or other) may be hard or easy depending on the type of queueing system at hand**  •  $L = \sum_{n=0}^{\infty} nP_n$  ( $P_n$ : probability that *n* customers are in the system)





## **The differential equations that determine the state probabilities**   $P_n(t + \Delta t) = P_{n+1}(t) \cdot \mu_{n+1} \cdot \Delta t + P_{n-1}(t) \cdot \lambda_{n-1} \cdot \Delta t + P_n(t) \cdot [1 - (\mu_n + \lambda_n) \cdot \Delta t]$

**After a simple manipulation:** 

$$
\frac{dP_n(t)}{dt} = -(\lambda_n + \mu_n) \cdot P_n(t) + \lambda_{n-1} \cdot P_{n-1}(t) + \mu_{n+1} \cdot P_{n+1}(t) \tag{1}
$$

 $(1)$  applies when  $n = 1, 2, 3, \ldots$ ; when  $n = 0$ , we have:

$$
\frac{dP_0(t)}{dt} = -\lambda_0 \cdot P_0(t) + \mu_1 \cdot P_1(t)
$$
\n(2)

• **The system of equations (1) and (2) is known as the Chapman-Kolmogorov equations for a birth-and-death system** 

#### **The "state balance" equations**  • **We now consider the situation in which the queueing**  *t* **is large enough to have**  $P_n(t) = P_n$ , independent of t, or  $\frac{dP_n(t)}{dt} = 0$ • **Then, (1) and (2) provide the state balance equations:**  • **The state balance equations can also be written directly from the state transition diagram**   $(\lambda_n + \mu_n) \cdot P_n = \lambda_{n-1} \cdot P_{n-1} + \mu_{n+1} \cdot P_{n+1}$   $n = 1, 2, 3,...$  (4)  $n=0$  (3)  $\lambda_0 \cdot P_0 = \mu_1 \cdot P_1$   $n =$ **system has reached "steady state", i.e.,**   $\boldsymbol{r}) = \boldsymbol{P_n}$ , independent of t, or



