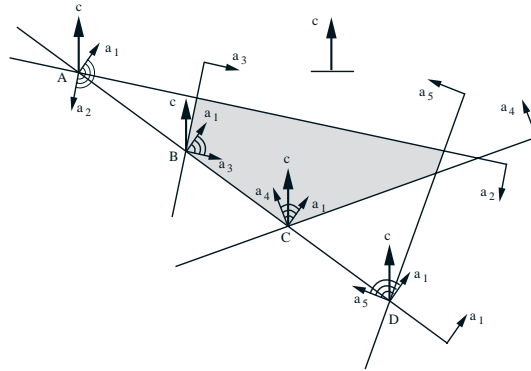


15.093 Optimization Methods

Lecture 6: Duality Theory II



1 Outline

SLIDE 1

- Geometry of duality
- The dual simplex algorithm
- Farkas lemma
- Duality as a proof technique

2 The Geometry of Duality

SLIDE 2

$$\begin{aligned}
 \min \quad & c'x \\
 \text{s.t.} \quad & a_i'x \geq b_i, \quad i = 1, \dots, m \\
 \\
 \max \quad & p'b \\
 \text{s.t.} \quad & \sum_{i=1}^m p_i a_i = c \\
 & p \geq 0
 \end{aligned}$$

3 Dual Simplex Algorithm

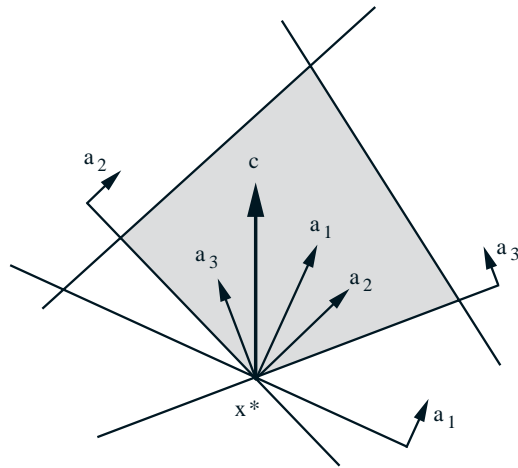
3.1 Motivation

SLIDE 3

- In simplex method $B^{-1}b \geq 0$
- Primal optimality condition

$$c' - c'_B B^{-1} A \geq 0'$$

same as **dual feasibility**



- Simplex is a **primal algorithm**: maintains **primal feasibility** and works towards **dual feasibility**
- **Dual algorithm**: maintains **dual feasibility** and works towards **primal feasibility**

SLIDE 4

$-c'_B x_B$	\bar{c}_1	\dots	\bar{c}_n
$x_{B(1)}$			
\vdots			
$x_{B(m)}$		$B^{-1}A_1 \quad \dots \quad B^{-1}A_n$	

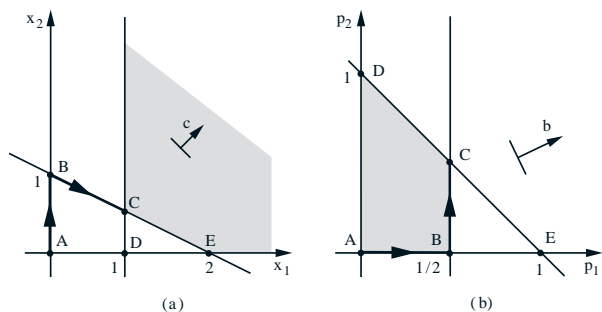
- Do not require $B^{-1}b \geq 0$
- Require $\bar{c} \geq 0$ (dual feasibility)
- Dual cost is

$$p'b = c'_B B^{-1}b = c'_B x_B$$
- If $B^{-1}b \geq 0$ then both dual feasibility and primal feasibility, and also same cost \Rightarrow **optimality**
- Otherwise, change basis

3.2 An iteration

SLIDE 5

1. Start with basis matrix B and all reduced costs ≥ 0 .
2. If $B^{-1}b \geq 0$ optimal solution found; else, choose l s.t. $x_{B(l)} < 0$.



3. Consider the l th row (pivot row) $x_{B(l)}, v_1, \dots, v_n$. If $\forall i v_i \geq 0$ then dual optimal cost = $+\infty$ and algorithm terminates.

SLIDE 6

4. Else, let j s.t.

$$\frac{\bar{c}_j}{|v_j|} = \min_{\{i|v_i < 0\}} \frac{\bar{c}_i}{|v_i|}$$

5. Pivot element v_j : A_j enters the basis and $A_{B(l)}$ exits.

3.3 An example

SLIDE 7

$$\begin{aligned} \min \quad & x_1 + x_2 \\ \text{s.t.} \quad & x_1 + 2x_2 \geq 2 \\ & x_1 \geq 1 \\ & x_1, x_2 \geq 0 \end{aligned}$$

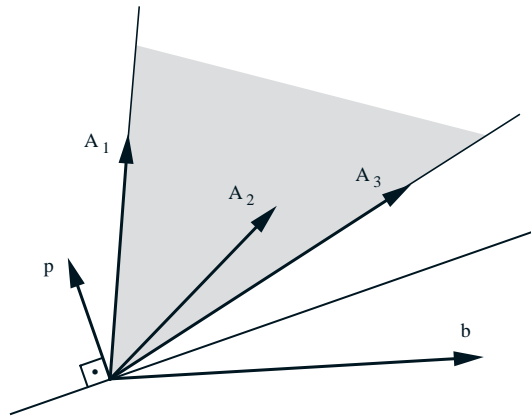
$$\begin{aligned} \min \quad & x_1 + x_2 & \max \quad & 2p_1 + p_2 \\ \text{s.t.} \quad & x_1 + 2x_2 - x_3 = 2 & \text{s.t.} \quad & p_1 + p_2 \leq 1 \\ & x_1 - x_4 = 1 & & 2p_1 \leq 1 \\ & x_1, x_2, x_3, x_4 \geq 0 & & p_1, p_2 \geq 0 \end{aligned}$$

SLIDE 8

	x_1	x_2	x_3	x_4
	0	1	1	0
$x_3 =$	-2	-1	-2*	1
$x_4 =$	-1	-1	0	0

SLIDE 9

	x_1	x_2	x_3	x_4
	-1	1/2	0	1/2
$x_2 =$	1	1/2	1	-1/2
$x_4 =$	-1	-1*	0	0



	x_1	x_2	x_3	x_4
$-3/2$	0	0	1/2	1/2
$x_2 =$	1/2	0	1	-1/2
$x_1 =$	1	1	0	-1

4 Duality as a proof method

4.1 Farkas lemma

SLIDE 10

Theorem:

Exactly one of the following two alternatives hold:

1. $\exists \mathbf{x} \geq \mathbf{0}$ s.t. $\mathbf{Ax} = \mathbf{b}$.
2. $\exists \mathbf{p}$ s.t. $\mathbf{p}'\mathbf{A} \geq \mathbf{0}'$ and $\mathbf{p}'\mathbf{b} < 0$.

4.1.1 Proof

SLIDE 11

“ \Rightarrow ” If $\exists \mathbf{x} \geq \mathbf{0}$ s.t. $\mathbf{Ax} = \mathbf{b}$, and if $\mathbf{p}'\mathbf{A} \geq \mathbf{0}'$, then $\mathbf{p}'\mathbf{b} = \mathbf{p}'\mathbf{Ax} \geq 0$

“ \Leftarrow ” Assume there is no $\mathbf{x} \geq \mathbf{0}$ s.t. $\mathbf{Ax} = \mathbf{b}$

$$\begin{array}{ll}
 (P) \max & \mathbf{0}'\mathbf{x} \\
 \text{s.t.} & \mathbf{Ax} = \mathbf{b} \\
 & \mathbf{x} \geq \mathbf{0}
 \end{array}
 \qquad
 \begin{array}{ll}
 (D) \min & \mathbf{p}'\mathbf{b} \\
 \text{s.t.} & \mathbf{p}'\mathbf{A} \geq \mathbf{0}'
 \end{array}$$

(P) infeasible \Rightarrow (D) either unbounded or infeasible

Since $\mathbf{p} = \mathbf{0}$ is feasible \Rightarrow (D) unbounded

$\Rightarrow \exists \mathbf{p} : \mathbf{p}'\mathbf{A} \geq \mathbf{0}'$ and $\mathbf{p}'\mathbf{b} < 0$