

15.093J Optimization Methods

Lecture 5: Duality Theory I

1 Outline

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- Motivation of duality
- General form of the dual
- Weak and strong duality
- Relations between primal and dual
- Economic Interpretation
- Complementary Slackness

2 Motivation

2.1 An idea from Lagrange

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Consider the LOP, called the **primal** with optimal solution \mathbf{x}^*

$$\begin{aligned} \min \quad & \mathbf{c}' \mathbf{x} \\ \text{s.t.} \quad & \mathbf{A} \mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq 0 \end{aligned}$$

Relax the constraint

$$\begin{aligned} g(\mathbf{p}) = \min \quad & \mathbf{c}' \mathbf{x} + \mathbf{p}' (\mathbf{b} - \mathbf{A} \mathbf{x}) \\ \text{s.t.} \quad & \mathbf{x} \geq 0 \end{aligned}$$

$$g(\mathbf{p}) \leq \mathbf{c}' \mathbf{x}^* + \mathbf{p}' (\mathbf{b} - \mathbf{A} \mathbf{x}^*) = \mathbf{c}' \mathbf{x}^*$$

Get the tightest lower bound, i.e.,

$$\max g(\mathbf{p})$$

$$\begin{aligned} g(\mathbf{p}) &= \min_{\mathbf{x} \geq 0} [\mathbf{c}' \mathbf{x} + \mathbf{p}' (\mathbf{b} - \mathbf{A} \mathbf{x})] \\ &= \mathbf{p}' \mathbf{b} + \min_{\mathbf{x} \geq 0} (\mathbf{c}' - \mathbf{p}' \mathbf{A}) \mathbf{x} \end{aligned}$$

Note that

$$\min_{\mathbf{x} \geq 0} (\mathbf{c}' - \mathbf{p}' \mathbf{A}) \mathbf{x} = \begin{cases} 0, & \text{if } \mathbf{c}' - \mathbf{p}' \mathbf{A} \geq \mathbf{0}', \\ -\infty, & \text{otherwise.} \end{cases}$$

$$\text{Dual} \quad \max g(\mathbf{p}) \Leftrightarrow \max_{\text{s.t.}} \frac{\mathbf{p}' \mathbf{b}}{\mathbf{p}' \mathbf{A} \leq \mathbf{c}'}$$

3 General form of the dual

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Primal		Dual
$\min c'x$		$\max p'b$
s.t.	$a_i'x \geq b_i \quad i \in M_1$	s.t. $p_i \geq 0 \quad i \in M_1$
	$a_i'x \leq b_i \quad i \in M_2$	$p_i \leq 0 \quad i \in M_1$
	$a_i'x = b_i \quad i \in M_3$	$p_i > 0 \quad i \in M_3$
	$x_j \geq 0 \quad j \in N_1$	$p' A_j \leq c_j \quad j \in N_1$
	$x_j \leq 0 \quad j \in N_2$	$p' A_j \geq c_j \quad j \in N_2$
	$x_j > 0 \quad j \in N_3$	$p' A_j = c_j \quad j \in N_3$

3.1 Example

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$\min x_1 + 2x_2 + 3x_3$	$\max 5p_1 + 6p_2 + 4p_3$
s.t. $-x_1 + 3x_2 = 5$	s.t. p_1 free
$2x_1 - x_2 + 3x_3 \geq 6$	$p_2 \geq 0$
$x_3 \leq 4$	$p_3 \leq 0$
$x_1 \geq 0$	$-p_1 + 2p_2 \leq 1$
$x_2 \leq 0$	$3p_1 - p_2 \geq 2$
x_3 free,	$3p_2 + p_3 = 3.$

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Primal	min	max	dual
constraints	$\geq b_i$	≥ 0	variables
	$\leq b_i$	≤ 0	
	$= b_i$	> 0	
variables	≥ 0	$\leq c_j$	constraints
	≤ 0	$\geq c_j$	
	> 0	$= c_j$	

Theorem: The dual of the dual is the primal.

3.2 A matrix view

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$\min c'x$	$\max p'b$
s.t. $Ax = b$	s.t. $p'A \leq c'$
$x \geq 0$	
$\min c'x$	$\max p'b$
s.t. $Ax \geq b$	s.t. $p'A = c'$
	$p \geq 0$

4 Weak Duality

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Theorem:

If x is primal feasible and p is dual feasible then $p'b \leq c'x$

Proof

$$p'b = p'Ax \leq c'x$$

Corollary:

If \mathbf{x} is primal feasible, \mathbf{p} is dual feasible, and $\mathbf{p}'\mathbf{b} = \mathbf{c}'\mathbf{x}$, then \mathbf{x} is optimal in the primal and \mathbf{p} is optimal in the dual.

5 Strong Duality

Theorem: If the LOP has optimal solution, then so does the dual, and optimal costs are equal.

Proof:

$$\begin{aligned} \min \quad & \mathbf{c}'\mathbf{x} \\ \text{s.t.} \quad & \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq 0 \end{aligned}$$

Apply Simplex; optimal solution \mathbf{x} , basis \mathbf{B} .

Optimality conditions:

$$\mathbf{c}' - \mathbf{c}'_{\mathbf{B}} \mathbf{B}^{-1} \mathbf{A} \geq \mathbf{0}'$$

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$$\text{Define } \mathbf{p}' = \mathbf{c}'_{\mathbf{B}} \mathbf{B}^{-1} \Rightarrow \mathbf{p}' \mathbf{A} \leq \mathbf{c}'$$

$\Rightarrow \mathbf{p}$ dual feasible for

$$\begin{aligned} \max \quad & \mathbf{p}'\mathbf{b} \\ \text{s.t.} \quad & \mathbf{p}' \mathbf{A} \leq \mathbf{c}' \end{aligned}$$

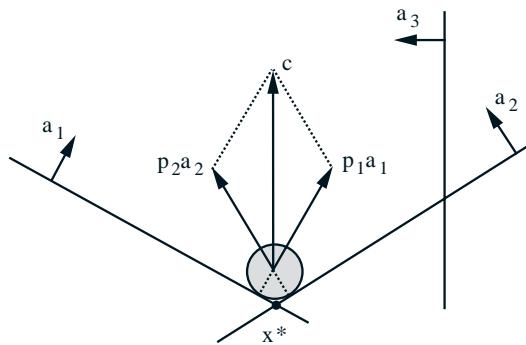
$$\mathbf{p}'\mathbf{b} = \mathbf{c}'_{\mathbf{B}} \mathbf{B}^{-1} \mathbf{b} = \mathbf{c}'_{\mathbf{B}} \mathbf{x}_{\mathbf{B}} = \mathbf{c}'\mathbf{x}$$

$\Rightarrow \mathbf{x}, \mathbf{p}$ are primal and dual optimal

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5.1 Intuition

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6 Relations between primal and dual

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	Finite opt.	Unbounded	Infeasible
Finite opt.	*		
Unbounded			*
Infeasible		*	*

7 Economic Interpretation

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- \mathbf{x} optimal nondegenerate solution: $\mathbf{B}^{-1}\mathbf{b} > \mathbf{0}$
- Suppose \mathbf{b} changes to $\mathbf{b} + \mathbf{d}$ for some small \mathbf{d}
 - How is the optimal cost affected?
 - For small \mathbf{d} feasibility unaffected
 - Optimality conditions unaffected
 - New cost $c'_B \mathbf{B}^{-1}(\mathbf{b} + \mathbf{d}) = \mathbf{p}'(\mathbf{b} + \mathbf{d})$
 - If resource i changes by d_i , cost changes by $p_i d_i$: “Marginal Price”

8 Complementary slackness

8.1 Theorem

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Let \mathbf{x} primal feasible and \mathbf{p} dual feasible. Then \mathbf{x}, \mathbf{p} optimal if and only if

$$p_i(\mathbf{a}'_i \mathbf{x} - b_i) = 0, \quad \forall i$$

$$x_j(c_j - \mathbf{p}' \mathbf{A}_j) = 0, \quad \forall j$$

8.2 Proof

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- $u_i = p_i(\mathbf{a}'_i \mathbf{x} - b_i)$ and $v_j = (c_j - \mathbf{p}' \mathbf{A}_j)x_j$
- If \mathbf{x}, \mathbf{p} primal and dual feasible, $u_i \geq 0, v_j \geq 0 \quad \forall i, j$.
- Also $\mathbf{c}'\mathbf{x} - \mathbf{p}'\mathbf{b} = \sum_i u_i + \sum_j v_j$.
- By the strong duality theorem, if \mathbf{x} and \mathbf{p} are optimal, then $\mathbf{c}'\mathbf{x} = \mathbf{p}'\mathbf{b} \Rightarrow u_i = v_j = 0$ for all i, j .
- Conversely, if $u_i = v_j = 0$ for all i, j , then $\mathbf{c}'\mathbf{x} = \mathbf{p}'\mathbf{b}$,
- $\Rightarrow \mathbf{x}$ and \mathbf{p} are optimal.

8.3 Example

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$$\begin{array}{ll} \min & 13x_1 + 10x_2 + 6x_3 \\ \text{s.t.} & 5x_1 + x_2 + 3x_3 = 8 \\ & 3x_1 + x_2 = 3 \\ & x_1, x_2, x_3 \geq 0 \end{array} \quad \begin{array}{ll} \max & 8p_1 + 3p_2 \\ \text{s.t.} & 5p_1 + 3p_2 \leq 13 \\ & p_1 + p_2 \leq 10 \\ & 3p_1 \leq 6 \end{array}$$

Is $\mathbf{x}^* = (1, 0, 1)'$ optimal?

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$$5p_1 + 3p_2 = 13, \quad 3p_1 = 6$$

$$\Rightarrow p_1 = 2, \quad p_2 = 1$$

Objective=19