

3.40J / 22.71J
Modern Physical Metallurgy
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Lecture 6: Dislocation self-energy and interactions

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Dislocation identification

Dislocation line ξ and dislocation Burgers vector completely define the dislocation, telling you where and how easily it will move.

Dislocation line ξ :
defines the long dimension of the extra half-plane

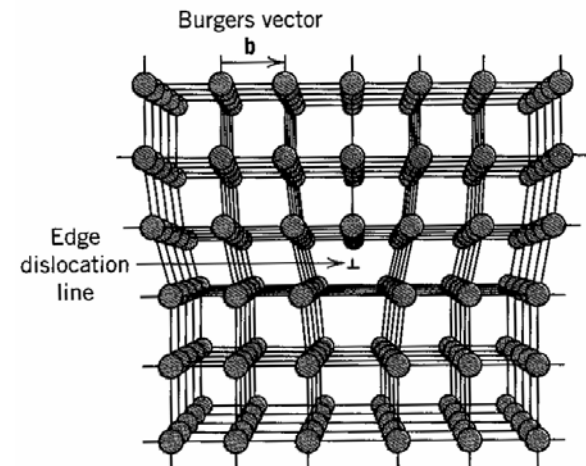
Dislocation slip direction \mathbf{b} :
defines the vector that closes a complete circuit of lattice sites in an imperfect crystal
defines the direction of atomic motion during deformation

RHFS Convention (only):
Draw RH circuit that contains dislocation
Draw vector from finish point to start point = \mathbf{b}

Go to next slide and show the circuit

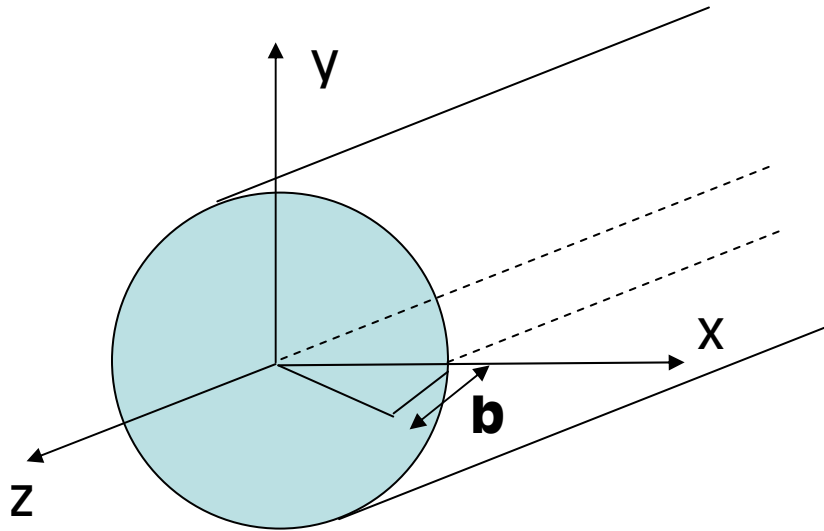
How edge and screw are different:

Edge	\mathbf{b} perpendicular to ξ moves parallel to \mathbf{b}
Screw	\mathbf{b} parallel to ξ moves perpendicular to \mathbf{b}

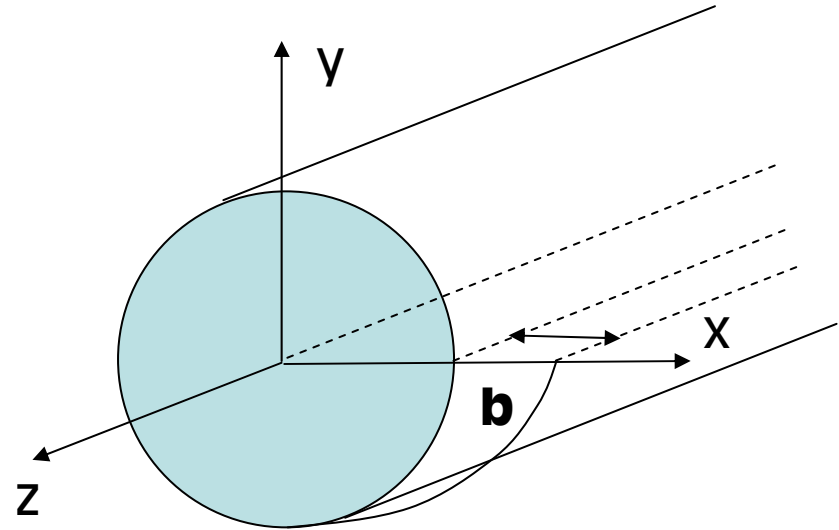


Elastic energy of dislocation:

Distortion around straight dislocation is like a cylinder of strained material

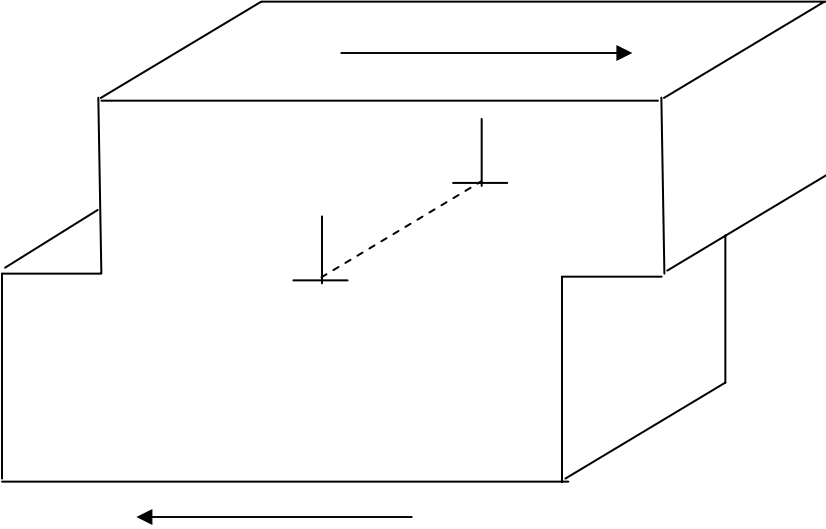


Screw dislocation displacement field:



Edge dislocation displacement field:

Force acting on a dislocation:



Peach-Kohler formulation for calculating effects of stress acting on a dislocation line:

Mental process:

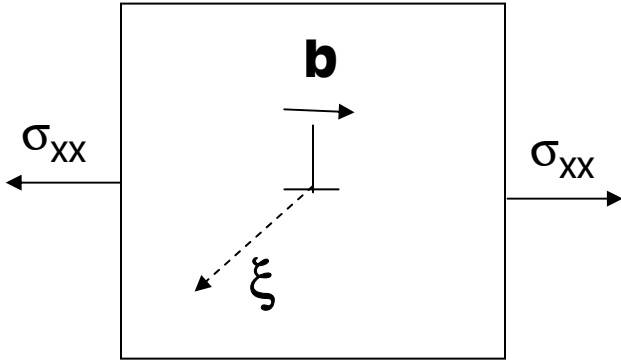
(1)

(2)

(3)

If a uniform stress S acts on the dislocation line, it does work:

Example of Peach-Kohler:



How does a dislocation move in the presence of a tensile stress σ_{xx} ?

Application to metals:

(1) Hydrogen embrittlement:

(2) Serrated yielding: