

IMPLEMENTATION OF AN OPTIMAL MULTICOMMODITY NETWORK FLOW
ALGORITHM BASED ON GRADIENT PROJECTION AND A PATH FLOW FORMULATION[†]

by

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ABSTRACT

The implementation of a multicommodity flow algorithm into a FORTRAN code is discussed. The algorithm is based on a gradient projection method [1] with diagonal scaling based on Hessian or Jacobian information. The flows carried by the active paths of each origin-destination (OD) pair are iterated upon one OD pair at a time. Active paths are generated using a shortest path algorithm--one path per OD pair, per iteration. The data structures and memory requirements of the algorithm are discussed and are compared with those of other formulations based on link flows associated with each origin, and aggregate link flows.

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1. Optimal Multicommodity Flow Problem Formulation

We have a directed network with set of nodes N and set of links L . Let W be a collection of ordered node pairs referred to as origin-destination (OD) pairs. For each OD pair $w \in W$ we are given a positive number r_w representing input flow into the network from origin to destination. Let P_w be a given set of directed paths joining the origin node and destination node of OD pair w . (P_w could be the set of all simple directed paths joining origin and destination, or it could be a restricted set of paths determined a priori on the basis of some unspecified considerations). Note that we do not exclude the possibility that two distinct OD pairs have the same origin and destination and possibly a different set of paths, but are associated with different classes or types of traffic.

Let x_p be the flow carried by a generic path p . The optimization variables of the problem are x_p , $p \in P_w$, $w \in W$ and must satisfy the constraints

$$\sum_{p \in P_w} x_p = r_w \quad , \quad \forall w \in W, \quad (1)$$

$$x_p \geq 0 \quad , \quad \forall p \in P_w, w \in W. \quad (2)$$

Let x be the vector of all path flows

$$x = \{x_p \mid p \in P_w, w \in W\} \quad (3)$$

For each link (i,j) and OD pair w we are given a continuously differentiable function $T_{ij}(x,w)$, which is to be interpreted as the length of link (i,j) when the path flow vector is x . In data communication routing and traffic assignment problems $T_{ij}(x,w)$ usually has the interpretation of

marginal delay and travel time respectively (see [1]-[19]). We assume that for all feasible x and all $w \in W$

$$T_{ij}(x,w) \geq 0 \quad , \quad \forall (i,j) \in L \quad , \quad (4)$$

The length of a path $p \in P_w$ when the path flow vector is x is defined by

$$L_p(x,w) = \sum_{(i,j) \in p} T_{ij}(x,w) \quad (5)$$

i.e. it is the sum of lengths of its links.

The problem we are considering is the following:

Find a path flow vector x^* satisfying the constraints (1), (2) and such that for every $w \in W$ and $p \in P_w$

$$x_p^* > 0 \implies L_p(x^*,w) \leq L_{p'}(x^*,w), \quad \forall p' \in P_w. \quad (6)$$

In other words we are looking for a path flow pattern x^* whereby the only paths that carry positive flow are shortest paths with respect to the link lengths $T_{ij}(x^*,w)$.

The problem described above includes, among others, problems of optimal routing in data networks [1]-[8] and (possibly asymmetric) traffic assignment problems in transportation networks [9]-[19]. We refer to the references just cited for extensive discussions. The survey paper [1] describes in detail the data communication context. A typical formulation there is to find a feasible path flow vector x that minimizes

$$\sum_{(i,j)} D_{ij}(F_{ij}) \quad (7)$$

where D_{ij} is a monotonically increasing, twice differentiable function of the total flow F_{ij} of the link (i,j) given by

$$F_{ij} = \sum_{w \in W} \sum_{p \in P_w} x_p \delta(p,i,j) \quad (8)$$

where

$$\delta(p,i,j) = \begin{cases} 1 & \text{if link } (i,j) \text{ belong to path } p \\ 0 & \text{otherwise.} \end{cases} \quad (9)$$

It can be shown (see e.g. [1]) that if we make the identification

$$T_{ij} = D'_{ij} : \text{ The first derivative of } D_{ij} \quad (10)$$

the routing optimization problem falls within the framework of the general multicommodity flow problem described earlier.

2. A Projection Method for Solving the Multicommodity Flow Problem

The MULTIFLO and MULTIFLO1 codes given in Appendices I and II of this report implement an algorithm that solves the problem of the previous section for the case where for all OD pairs $w \in W$

P_w = Set of all simple paths joining the origin and destination of w .

The set of OD pairs is divided into C groups called commodities. All OD pairs of a commodity have the same origin node. Furthermore the data structures of the codes can handle only the case where the lengths $T_{ij}(x,w)$ depend on w through the corresponding commodity c . That is

$$T_{ij}(x,w) = T_{ij}(x,\bar{w}), \quad \forall (i,j) \in L, \text{ and OD pairs } w, \bar{w} \text{ of the same commodity } c.$$

It is also assumed that for all feasible F

$$\frac{\partial T_{ij}}{\partial x_p} \geq 0 \quad \forall (i,j) \text{ belonging to the path } p$$

MULTIFLO and MULTIFLO1 operate as follows:

At the beginning of the k th iteration we have for the generic OD pair $w \in W$ a set of active paths P_w^k consisting of at most $(k-1)$ paths. (These paths were generated in earlier iterations and it is implicitly assumed that all other paths carry zero flow). The following calculation is executed sequentially for each commodity--first for commodity 1, then for commodity 2, and so on up to the last commodity C :

Step 1: A shortest path that joins the origin node for the commodity with all other nodes is calculated. The length for each link (i,j) used for this calculation is $T_{ij}(x,w)$ where x is the current path flow vector. These shortest paths are added to the corresponding list of active paths of each OD pair of the commodity if they are not already there, so now the list of active paths for each OD pair of the commodity contains at most k paths.

Step 2: Each OD pair w of the commodity is taken up sequentially. For each active path p of w the length L_p [cf. (5)] is calculated together with an additional number α_p called the stepsize (more on the choice of this later). Both L_p and α_p are calculated on the basis of the current total link flow vector. Let \bar{p} be the shortest path calculated in Step 1 for the OD pair. The path flows of all paths $p \neq \bar{p}$ are updated according to

$$x_p \leftarrow \begin{cases} \max \{0, x_p - \alpha_p (L_p - L_{\bar{p}})\} & \text{if } L_p > L_{\bar{p}} \\ x_p & \text{otherwise.} \end{cases} \quad (11)$$

The path flow of the shortest path \bar{p} is then adjusted so that the sum of flows of all active paths equals r_w as required by the constraint (1), i.e.

$$x_{\bar{p}} \leftarrow r_w - \sum_{\text{active } p \neq \bar{p}} x_p. \quad (12)$$

In other words an amount x_p or $\alpha_p (L_p - L_{\bar{p}})$ is shifted from each nonshortest path to the shortest path \bar{p} --whichever is smaller. The total link flows F_{ij} are adjusted to reflect the changes in x_p and $x_{\bar{p}}$.

The rationale for iteration (11) is explained in [1], [6], [8], [9].

It is based on a gradient projection method [9], [21]. Note that it is possible that $L_p < L_{\bar{p}}$ for some $p \neq \bar{p}$ even though \bar{p} was calculated earlier as a shortest path. The reason is that by the time L_p and $L_{\bar{p}}$ are computed the total link flow vector may have changed since the time the shortest path has been calculated due to iterations on the path flows of other OD pairs of the same commodity.

Regarding the choice of the stepsize α_p , the MULTIFLO and MULTIFLO1 codes use the following formula for all $p \neq \bar{p}$

$$\alpha_p = S_p^{-1} \quad (13)$$

where

$$S_p = \sum_{(i,j) \in L_p} \frac{\partial T_{ij}}{\partial x_p} \quad (14)$$

and L_p is the set of links

$$L_p = \{(i,j) \mid (i,j) \text{ belongs to either } p \text{ or } \bar{p}, \\ \text{but not to both } p \text{ and } \bar{p}\}.$$

The rationale for this is as follows:

If we interpret the algorithm as one that tries to satisfy the equation

$$\bar{L}_p - L_{\bar{p}} = 0, \quad \forall p \text{ with } x_p > 0, \quad (16)$$

a natural choice for α_p is

$$\hat{\alpha}_p = \frac{\Delta x_p}{\Delta(L_p - L_{\bar{p}})} \quad (17)$$

where $\Delta(L_p - L_{\bar{p}})$ is the variation of $(L_p - L_{\bar{p}})$ resulting from a small variation

Δx_p in the path flow x_p (and an attendant variation $-\Delta x_p$ in the path flow $x_{\bar{p}}$). This corresponds to an approximate form of Newton's method whereby only the diagonal elements of the Jacobian matrix (corresponding to the current OD pair) are taken into account while the off-diagonal terms are set to zero (see also [1] for further discussion). For $\Delta x_p \rightarrow 0$ it is easily seen that (17) yields

$$\hat{\alpha}_p^{-1} = \sum_{(i,j) \in p} \left(\frac{\partial T_{ij}}{\partial x_p} - \frac{\partial T_{ij}}{\partial x_{\bar{p}}} \right) + \sum_{(i,j) \in \bar{p}} \left(\frac{\partial T_{ij}}{\partial x_{\bar{p}}} - \frac{\partial T_{ij}}{\partial x_p} \right). \quad (18)$$

In most cases of interest we have

$$\frac{\partial T_{ij}}{\partial x_p} \approx \frac{\partial T_{ij}}{\partial x_{\bar{p}}} \quad \text{if } (i,j) \in p \text{ and } (i,j) \in \bar{p}$$

$$\frac{\partial T_{ij}}{\partial x_p} \approx 0 \quad \text{if } (i,j) \notin p$$

$$\frac{\partial T_{ij}}{\partial x_{\bar{p}}} \approx 0 \quad \text{if } (i,j) \notin \bar{p}$$

so (18) becomes approximately [c.f. (18), (14)]

$$\hat{\alpha}_p^{-1} \approx \sum_{(i,j) \in L_p} \frac{\partial T_{ij}}{\partial x_p} = S_p,$$

thereby justifying the use of the stepsize (13), (14).

If one wishes to employ the formula (18) for the stepsize it is necessary to modify the codes. These modifications should not be too

difficult for an experienced user. Another possibility is to use a smaller value of stepsize α_p than the one given by (13)--for example $\alpha_p = \rho S_p^{-1}$ $\rho \in (0,1)$ is a fixed relaxation parameter. (A smaller stepsize enhances the convergence properties of the algorithm but may deteriorate its rate of convergence). This can be accomplished without any changes in the code by simply introducing the relaxation parameter ρ in the subroutine that calculates $\frac{\partial T_{ij}}{\partial x_p}$ [cf. (14)].

In the MULTIFLO code a shortest path tree is generated and stored at each iteration for each commodity. As a result the memory storage for shortest paths is proportional to the number of iterations so for large problems one cannot execute a large number of iterations without incurring a heavy penalty for disk I/O. MULTIFLO will usually find in five to ten iterations what is for most practical problems an adequate approximation to an optimal solution. This is particularly true of lightly loaded networks (e.g. with utilization of all links less than 60% at the optimum). For heavily loaded networks the number of required iterations usually tends to be larger (say 10-30). It should be a rare occasion when a user will require more than thirty iterations for his practical problem.

MULTIFLO1 differs from MULTIFLO only in the method used for storing the active paths. MULTIFLO1 stores explicitly all active paths in a single array rather than storing them implicitly through the generated shortest path trees. As a result the memory storage of MULTIFLO1 depends on the number of active paths generated and is largely independent of the number of iterations executed. For certain problems including situations where a large number of iterations is desired MULTIFLO1 may hold a storage advantage over MULTIFLO. Both codes generate identical numerical results although MULTIFLO1 appears to be somewhat faster on sample test problems.

3. Data Structures for Representing the Problem

The data structures of MULTIFLO and MULTIFLO1 are described in the code documentation. The problem input structure will be illustrated here by means of the 5 node-6 link network shown in Figure 1:

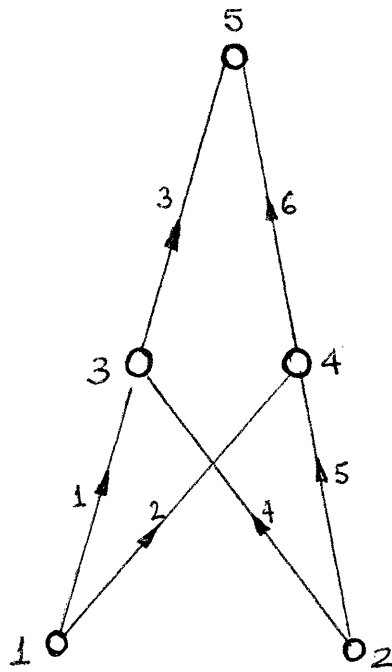


Figure 1

Node Length Arrays (FRSTOU, LASTOU):

These arrays specify the network topology.

FRSTOU(NODE): The first link out of NODE

LASTOU(NODE): The last link out of NODE

NODE	FRSTOU	LASTOU
1	1	2
2	4	5
3	3	3
4	6	6
5	0	0

Note that all arcs with the same head node must be grouped together in the arc list. A node with no outgoing links is recognized via FRSTOU = 0

Arc Length Arrays (STARTNODE, ENDNODE)

These arrays also specify the network topology:

STARTNODE (ARC): The head node of ARC

ENDNODE (ARC): The tail node of ARC

ARC	STARTNODE	ENDNODE
1	1	3
2	1	4
3	3	5
4	2	3
5	2	4
6	4	5

Commodity Length Arrays (ORGID, STARTOD)

ORGID (COMMODITY): The origin node of COMMODITY

STARTOD (COMMODITY): A pointer to the first OD pair of COMMODITY on the OD pair list

For the example of Figure 1 we will assume three commodities

COMMODITY	ORGID	STARTOD
1	2	1
2	1	3
3	1	4

Note that it is required that OD pairs are listed sequentially by commodity, i.e. the OD pairs of commodity 1 are listed first, followed by the OD pairs of commodity 2, etc. Therefore the STARTOD array together with the total number of OD pairs specify all OD pairs associated with each commodity.

OD Pair Length Arrays (DEST, INPUT_FLOW)

DEST(OD): The destination node of OD

INPUT_FLOW(OD): The input traffic of OD

OD	DEST	INPUT_FLOW
1	3	problem dependent
2	5	"
3	3	"
4	4	"
5	5	"

From the arrays ORGID, STARTOD and DEST together with the total number of OD pairs the set of OD pairs corresponding to each commodity is completely specified. For our example these are:

COMMODITY	OD PAIRS
1	(2,3), (2,5)
2	(1,3)
3	(1,4), (1,5)

Additional input information is required to calculate the link lengths T_{ij} and their first derivatives $\frac{\partial T_{ij}}{\partial x_p}$ in the subroutine DERIVS and DERIV1. This is of course problem dependent. The listing of Appendix I gives an example which is typical of routing problems in data networks [cf. equations (7)-(10)].

4. Memory Requirements - Comparisons with Other Methods

The memory storage requirements of both MULTIFLO and MULTIFLO1 are substantial, but this is true for all methods that provide as output not only the optimal total link flows but also detailed information about the optimal routing from origins to destinations (i.e. optimal path flows).

Assuming that 1 byte is allocated for a logical variable, 2 bytes are allocated for storing a node or link identification number and an iteration number, 4 bytes are allocated for storing a commodity, OD pair or path identification number, and 4 bytes are allocated for storing a real number (e.g. a path or link flow) the total array storage in bytes of MULTIFLO during execution is

$$6n_N + 9n_L + 6n_C + 6n_{OD} + 10n_P + 2n_I n_N n_C \quad (19)$$

where:

n_N : Number of nodes

n_L : Number of links

n_C : Number of commodities

n_{OD} : Number of OD pairs

n_P : Number of active paths generated

n_I : Number of iterations.

Additional storage is required for information necessary to calculate link lengths and their derivatives but this is typically of order $O(n_L)$ and is not significant.

The dominant array as far as storage of MULTIFLO is concerned is the

triple indexed PRED array which stores the shortest path trees generated for each commodity at each iteration. This array accounts for the last term $2n_I n_N n_C$ in (19). The term $10n_P$ is also substantial since the number of active paths n_P can be as large as $n_I n_{OD}$. However, because the algorithm stores a path only once at the iteration it is first generated and does not duplicate it if it is generated again later, the actual number n_P is typically much smaller than $n_I n_{OD}$. This was confirmed by extensive computational experimentation, that showed that except for very heavily loaded networks the actual number of active paths n_P was typically no more than $2n_{OD}$ (!) and often considerably less. We conclude therefore that the dominant bottleneck for storage is the shortest path description array PRED requiring $2n_I n_N n_C$ bytes.

In the MULTIFLO1 code the array PRED is not used. In its place the array PDESCR is used which requires storage of $2n_P n_N$ at most. This calculation assumes conservatively that a path has n_N links. However in practice the actual storage for PDESCR is several times less than $2n_P n_N$. If we adopt the rough estimate $n_P \approx 2n_{OD}$ then we conclude that the storage requirements of MULTIFLO and MULTIFLO1 are roughly comparable if the number of iterations n_I is comparable to something between $\frac{n_{OD}}{4n_C}$ and $\frac{n_{OD}}{n_C}$ with MULTIFLO1 becoming definitely preferable if $n_I \approx \frac{n_{OD}}{n_C}$. MULTIFLO1 is also preferable for problems that are solved repetitively with minor variations in their data since then the knowledge of the path description array PDESCR can be fruitfully exploited. This is not possible with MULTIFLO.

In large problems where only the total link flows are of interest (e.g. traffic assignment problems) a different algorithm [e.g. the flow

Deviation (or the Frank-Wolfe) method [3], [8] or the Cantor-Gerla (or simplicial approximation) method [4], [15], may be preferable over MULTIFLO or MULTIFLO1, since then storage of order $O(n_L)$ or perhaps $O(n_I n_L)$ is required. However when detailed routing information is of interest the memory storage requirements of MULTIFLO are competitive with those of other methods based on shortest paths including the Flow Deviation and Cantor-Gerla methods. The reason is that detailed routing information can be provided by these methods only if the shortest paths generated at each iteration are stored explicitly in an array such as PRED, and as mentioned earlier this is the main memory storage bottleneck.

There are algorithms that can solve multicommodity flow problems and provide detailed routing information without requiring the generation and storage of shortest paths. These algorithms are based on a link flow formulation [20], or the link flow fraction formulation due to Gallager [2], [5], [7] whereby the optimization variables are the flows or fractions of flow respectively for each commodity that are routed along each link. The storage requirement for these algorithms is of order $O(n_C n_L)$ and is independent of the number of iterations. When we compare this storage with the $O(n_I n_C n_L)$ storage of algorithms based on shortest paths we see that link flow formulations hold an advantage in terms of storage for problems where a large number of iterations is desirable. The reverse is true if the number of iterations required for adequate solution of the problem is small, or if the number of links is much larger than the number of nodes.

We finally note a final advantage of the path flow formulation over link flow formulations. When the set of paths for each OD pair is restricted to be a given strict subset of the set of all possible simple paths it is extremely cumbersome to use a link flow formulation. By contrast it is straightforward to modify the MULTIFLO1 code to handle this situation.

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APPENDIX I: MULTIFLO Code

The following FORTRAN code works on the VAX family of computers. It consists of a DRIVER program and several subroutines:

LOAD: Reads network topology and link length data from disk.

MULTIFLO: This is the main algorithm.

SP: Calculates a shortest path tree from an origin node to all other nodes.

PRFLOW: Prints out to disk problem data and algorithmic results.

DERIVS: This user supplied routine calculates for a given link (i,j) its length T_{ij} (D1CAL) and the length derivative $\frac{\partial T_{ij}}{\partial x_p}$ (D2CAL).

DERIV1: This routine is the same as DERIVS except that it calculates the length T_{ij} (D1CAL) but not the length derivative $\frac{\partial T_{ij}}{\partial x_p}$.

DELAY: This user supplied routine is useful only if the multicommodity flow problem is a routing optimization problem of the form (7)-(10) as described in Section 1. For asymmetric traffic assignment problems it has no purpose. It calculates the total delay

$$\sum_{(i,j)} D_{ij}(F_{ij})$$

where $D'_{ij} = T_{ij}$ [cf. (7)-(10)]. The value of $D_{ij}(F_{ij})$ is calculated using the function DCAL.

Two versions of the shortest path routine SP are provided (SHORTPAPE and SHORTEAP) which can be used interchangeably. SHORTEAP is recommended for problems where there are only few destinations for each commodity.

Otherwise SHORTPAPE based on [23] should be preferable.

A program (SETUP) is also provided for the purpose of creating the data describing the problem in a format that is compatible with the LOAD routine.

The routines LOAD, DERIV1, DERIVS, DELAY, and DCAL supplied in this appendix correspond to the most commonly solved optimal routing problem in data communication network applications whereby a capacity C_{ij} is given for each link (i,j) (this is the array BITRATE in the code) and

$$D_{ij}(F_{ij}) = \frac{F_{ij}}{C_{ij} - F_{ij}} \quad (\text{M/M/1 Queueing Delay}) \quad (\text{A.1})$$

$$T_{ij}(F_{ij}) = \frac{C_{ij}}{(C_{ij} - F_{ij})^2}$$

$$\frac{\partial T_{ij}(F_{ij})}{\partial F_{ij}} = \frac{2C_{ij}}{(C_{ij} - F_{ij})^3} .$$

Because $D_{ij}(F_{ij}) \rightarrow \infty$ as $F_{ij} \rightarrow C_{ij}$ these formulas have been modified so that if $F_{ij} \geq \rho C_{ij}$, where $\rho \in (0,1)$ is a parameter set by the user, then D_{ij} ,

T_{ij} , $\frac{\partial T_{ij}}{\partial F_{ij}}$ are calculated using a quadratic function which has the same value, first and second derivatives as $\frac{F_{ij}}{C_{ij} - F_{ij}}$ at the breakpoint ρC_{ij} .

In the program the parameter ρ is given by the variable MAXUTI set in the subroutine LOAD to 0.99. The user may wish to change this value.

The guideline is that ρ should be set at a value exceeding the maximum link utilization

$$\max_{(i,j) \in L} \frac{F_{ij}}{C_{ij}}$$

at the optimal solution. This trick gets around situations whereby the input flows are so large that exceeding some of the link capacities during some phase of the algorithm is inevitable.

The MULTIFLO code will stop computing when one of two conditions is met: Either the maximum number of iterations (MAXITER) is exceeded or a normalized measure of deviation from the optimal solution falls below a certain tolerance (TOL). This measure is roughly equal to the percentage of input traffic of an OD pair that does not lie on a shortest path (maximized over all OD pairs), and its magnitude is not substantially affected by the size of the problem. Both convergence parameters MAXITER and TOL are set by the user in the subroutine LOAD.


```
DESTOD=DEST (OD)
PATH=OD
DO WHILE (PATH.GT.0)
  WRITE (6,*) ORIGIN,DESTOD,PATH,FP (PATH)
  PATH=NEXTPATH (PATH)
END DO
500 CONTINUE
1000 CONTINUE
STOP
END
```



```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      LOAD
C
C      'LOAD' READS IN DATA FROM DISK CREATED WITH PROGRAM 'SETUP' FOR
C      USE BY PROGRAM 'MULTIFLO'. NETWORK SPECIFICATION DATA RESIDES
C      ON FORTRAN UNIT 01 AND NETWORK TRAFFIC SPECIFICATION DATA
C      RESIDES ON FORTRAN UNIT 02.
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
      SUBROUTINE LOAD
      IMPLICIT NONE
C
C      ***** INCLUDE COMMON BLOCKS *****
C
      INCLUDE 'PARAM.DIM'
      INCLUDE 'NETWRK.PRM'
      INCLUDE 'CONVRG.PRM'
C
C      ***** LOCAL VARIABLE DEFINITIONS *****
C
      INTEGER I
      DO LOOP INDEX
C
C      ***** EXECUTABLE CODE *****
C      TERMINATION PARAMETERS. MAXITER GIVES THE MAX # OF ITERATIONS
C      TOL IS A SOLUTION ACCURACY TOLERANCE. RECOMMENDED VALUES
C      ARE 0.01 TO 0.0001. THE PROPER VALUE OF TOL IS LARGELY
C      INDEPENDENT OF THE PROBLEM SIZE.
      MAXITER=20
      TOL=0.01
C      THE FOLLOWING PARAMETER MAKES SENSE ONLY FOR ROUTING PROBLEMS
C      WHERE AN M/M/1 QUEUING FORMULA IS USED FOR DELAY.
C      IT GIVES THE THRESHOLD FRACTION OF CAPACITY BEYOND WHICH
C      THE DELAY FORMULA IS TAKEN TO BE QUADRATIC.
      MAXUTI=0.99
C
C      LOAD THE NETWORK CONFIGURATION FROM FORTRAN UNIT 01
C
C      NODE SPECIFICATIONS
C
      READ(1,*)NN
      DO I=1,NN
        READ(1,*)FRSTOU(I),LASTOU(I)
      END DO
C
C      LINK SPECIFICATIONS
C
      READ(1,*)NA
C
C      BITRATE(I) IS A PARAMETER ASSOCIATED WITH LINK I. IN THE
C      DATA NETWORK ROUTING CONTEXT IT HAS THE MEANING OF
C      TRANSMISSION CAPACITY OF LINK I.
C
      DO I=1,NA
        READ(1,*)STARTNODE(I),ENDNODE(I),BITRATE(I)
      END DO
C
C      INPUT COMMODITY DATA FROM FORTRAN UNIT 02

```

C

```
READ (2,*) NUMCOMMOD
DO I=1, NUMCOMMOD
  READ (2,*) ORGID(I), STARTOD(I)
END DO
READ (2,*) NUMODPAIR
DO I=1, NUMODPAIR
  READ (2,*) DEST(I), INPUT_FLOW(I)
END DO
RETURN
END
```

CC
 C
 C MULTIFLO
 C
 C

C MULTICOMMODITY FLOW ALGORITHM BASED ON A PATH FLOW FORMULATION
 C UPDATES THE PATH FLOWS OF OD PAIRS ONE AT A TIME ACCORDING TO
 C AN ITERATION OF THE PROJECTION TYPE.
 C

C DEVELOPED BY DIMITRI BERTSEKAS, BOB GENDRON, AND WEI K TSAI
 C

C BASED ON THE PAPERS:
 C

- C 1) BERTSEKAS,D.P., "A CLASS OF OPTIMAL ROUTING ALGORITHMS
 C FOR COMMUNICATION NETWORKS", PROC. OF 5TH INTERNATIONAL
 C CONFERENCE ON COMPUTER COMMUNICATION (ICCC-80),
 C ATLANTA, GA., OCT. 1980, PP.71-76.
 C
 C 2) BERTSEKAS,D.P. AND GAFNI,E.M., "PROJECTION METHODS
 C FOR VARIATIONAL INEQUALITIES WITH APPLICATION TO
 C THE TRAFFIC ASSIGNMENT PROBLEM", MATH. PROGR. STUDY,17,
 C D.C.SORENSEN AND J.-B. WETS (EDS), NORTH-HOLLAND,
 C AMSTERDAM,1982, PP. 139-159.
 C
 C 3) BERTSEKAS,D.P., "OPTIMAL ROUTING AND FLOW CONTROL
 C METHODS FOR COMMUNICATION NETWORKS", IN ANALYSIS AND
 C OPTIMIZATION OF SYSTEMS, (PROC. OF 5TH INTERNATIONAL
 C CONFERENCE ON ANALYSIS AND OPTIMIZATION, VERSAILLES,
 C FRANCE), A. BENSOUSSAN AND J.L. LIONS (EDS),
 C SPRINGER-VERLAG, BERLIN & NY,1982, PP. 615-643.
 C
 C 4) BERTSEKAS,D.P. AND GAFNI, E.M., "PROJECTED NEWTON
 C METHODS AND OPTIMIZATION OF MULTICOMMODITY FLOWS",
 C IEEE TRANSACTIONS ON AUTOMATIC CONTROL, DEC. 1983.
 C

CC
 C
 C SUBROUTINE MULTIFLO
 C

C IMPLICIT NONE
 C

C ***** INCLUDE COMMON BLOCKS *****
 C

C INCLUDE 'PARAM.DIM'
 C INCLUDE 'NETWRK.PRM'
 C INCLUDE 'CONVRG.PRM'
 C INCLUDE 'PATHS.BLK'
 C

C NODE ARRAYS (LENGTH NN):
 C

C FRSTOU(NODE) - FIRST ARC OUT OF NODE
 C

C LASTOU(NODE) - LAST ARC OUT OF NODE
 C

C NOTE: THE ARC LIST MUST BE ORDERED IN SEQUENCE SO
 C

C THAT ALL ARCS OUT OF ANY NODE ARE GROUPED TOGETHER
 C

C ARC ARRAYS (LENGTH NA):
 C

C FA(ARC) - THE TOTAL FLOW OF ARC
 C

C STARTNODE(ARC) - THE HEAD NODE OF ARC
 C

C ENDNODE(ARC) - THE TAIL NODE OF ARC
 C
 C

C COMMODITY LENGTH ARRAYS (LENGTH NUMCOMMOD) :

C ORGID(COMMODITY) - THE NODE ID OF THE ORIGIN OF COMMODITY
C STARTOD(COMMODITY) - THE STARTING OD PAIR IN THE ODPAIR LIST
C CORRESPONDING TO THE ORIGIN IN POSITION RANK

C NOTE: THIS SCHEME ASSUMES THAT OD PAIRS ARE LISTED IN SEQUENCE
C I.E. THE OD PAIRS CORRESPONDING TO THE COMMODITY ONE
C ARE LISTED FIRST. THEY ARE
C FOLLOWED BY THE OD PAIRS OF THE COMMODITY TWO
C AND SO ON.

C ODPAIR ARRAYS (LENGTH NUMOD) :

C DEST(OD) - GIVES THE DESTINATION OF ODPAIR OD
C INPUT_FLOW(OD) - GIVES THE INPUT TRAFFIC OF ODPAIR OD

C PATH ARRAYS (LENGTH DYNAMICALLY UPDATED) :

C PATHID(PATH) - THE ITERATION # AT WHICH PATH WAS GENERATED
C NEXTPATH(PATH) - THE NEXT PATH FOR THE SAME OD PAIR FOLLOWING
C PATH. IT EQUALS 0 IF PATH IS THE LAST FOR THAT OD PAIR
C FP(PATH) - THE FLOW CARRIED BY PATH

C PATH DESCRIPTION LIST ARRAY (LENGTH MAXITER*NUMCOMD*NN)

C PRED(NODE,ITER,COMMODITY) - THIS TRIPLE INDEXED ARRAY SPECIFIES THE
C SHORTEST PATH TREE GENERATED AT ITERATION ITER
C & CORRESPONDING TO THE ORIGIN ASSOCIATED W/ COMMODITY
C IT GIVES THE LAST ARC ON THE SHORTEST PATH FROM ORIGIN TO NODE.

C ***** LOCAL VARIABLE DEFINITIONS *****

C INTEGER*2 PRED(NNN,NMAXITER,NNORIG)
C PATH DESCRIPTION ARRAY - CONTAINS SHORTEST
C PATH TREES FOR ALL ITERATIONS
C LOGICAL SPNEW
C LOGICAL INDICATING A NEW PATH FOUND
C LOGICAL SAME
C LOGICAL INDICATING A NEW SHORTEST PATH ALREADY EXISTING
C INTEGER NODE
C NODE IDENTIFIER
C INTEGER DESTOD
C THE DESTINATION NODE OF AN OD PAIR
C INTEGER ARC
C DO LOOP INDEX FOR ARCS
C INTEGER PATH
C A PATH INDEX
C INTEGER NUMLIST
C TOTAL NUMBER OF ACTIVE PATHS FOR OD PAIR UNDER CONSIDERATION
C INTEGER ITER
C SPECIFIC ITERATION
C INTEGER N1,N2
C TEMPORARY VARIABLES
C REAL MINFDER
C THE LENGTH FOR A SHORTEST PATH
C REAL MINSDER
C THE SECOND DERIVATIVE LENGTH FOR THE SHORTEST PATH
C REAL TMINSDER
C TEMPORARY VALUE FOR SECOND DERIVATIVE LENGTH OF SHORTEST PATH
C REAL INCR
C TOTAL SHIFT OF FLOW TO THE MINIMUM FIRST DERIVATIVE LENGTH PATH
C REAL PATHINCR
C SHIFT OF FLOW FOR A GIVEN PATH

```

REAL    FLOW
C      FLOW FOR A PATH
REAL    FDER
C      THE ACCRUED LENGTH ALONG A PATH
REAL    SDER
C      THE ACCRUED SECOND DERIVATIVE LENGTH ALONG A PATH
REAL    TEMPERROR
C      TEMPORARY STORAGE FOR CONVERGENCE ERROR
REAL    FDLLENGTH(NMAXITER)
C      ARRAY OF LENGTHS OF PATHS FOR AN OD PAIR
REAL    SDLENGTH(NMAXITER)
C      ARRAY OF SECOND DERIVATIVE LENGTHS OF PATHS FOR AN OD PAIR
INTEGER PATHLIST(NMAXITER)
C      ARRAY OF ACTIVE PATHS FOR AN OD PAIR
INTEGER COMMODITY
C      DO LOOP INDEX FOR THE OD PAIR ORIGINS
INTEGER ORIGIN
C      SPECIFIC ORIGIN
INTEGER I
C      DO LOOP INDEX
INTEGER OD
C      OD DO LOOP INDEX
INTEGER K
C      DO LOOP INDEX
INTEGER SHORTEST
C      THE SHORTEST PATH
LOGICAL MEMBER(NNA)
C      LOGICAL FOR AN ARC INCLUDED IN THE SHORTEST PATH
REAL    DLENGTH
C      DIFFERENCE IN PATH LENGTHS FOR THE TRAFFIC
REAL    D1CAL
C      ARC LENGTH
REAL    D2CAL
C      DERIVATIVE OF ARC LENGTH
C
C ***** EXECUTABLE CODE *****
C
C *****
C *   INITIALIZATION
C *****
C
DO 5 ARC=1,NA
  FA(ARC)=0.0
5 CONTINUE
C
DO I=1,NUMODPAIR
  FP(I)=INPUT_FLOW(I)
ENDDO
STARTOD(NUMCOMM+1)=NUMODPAIR+1
NUMPATH=0
NUMITER=1
DO 100 COMMODITY=1,NUMCOMM
  ORIGIN=ORGID(COMMODITY)
  CALL SP(ORIGIN,COMMODITY)
  DO 10 I=1,NN
    PRED(I,1,COMMODITY)=PA(I)
10 CONTINUE
C
C      LOOP OVER OD PAIRS OF COMMODITY
C

```

```

N1=STARTOD (COMMODITY)
N2=STARTOD (COMMODITY+1) -1
DO 50 OD=N1,N2
  NUMPATH=NUMPATH+1
  PATHID (NUMPATH)=1
  NEXTPATH (NUMPATH)=0
  FLOW=FP (NUMPATH)
  NODE=DEST (OD)
  DO WHILE (NODE.NE.ORIGIN)
    ARC=PA (NODE)
    FA (ARC)=FA (ARC)+FLOW
    NODE=STARTNODE (ARC)
  END DO
50   CONTINUE
100  CONTINUE
C
C   INITIALIZE THE MEMBER ARRAY
C
DO 70 ARC=1,NA
  MEMBER (ARC)=.FALSE.
70   CONTINUE
C
C   INITIALIZE THE TOTAL DELAY
C
CALL DELAY (DTOT (NUMITER) )
C
C   OUTPUT THE CURRENT INFORMATION TO DISK
C
CALL PREFLOW
C
C *****
C * END OF INITIALIZATION
C *****
C ***** START NEW ITERATION *****
C
110  NUMITER=NUMITER+1
    CURERROR=0
C
C ***** LOOP OVER ALL COMMODITIES *****
C
DO 1000 COMMODITY=1,NUMCOMMOD
  ORIGIN=ORGID (COMMODITY)
  CALL SP (ORIGIN,COMMODITY)
  DO 150 I=1,NN
    PRED (I,NUMITER,COMMODITY)=PA (I)
150  CONTINUE
C
C ***** LOOP OVER OD PAIRS OF COMMODITY
C
N1=STARTOD (COMMODITY)
N2=STARTOD (COMMODITY+1) -1
DO 500 OD=N1,N2
C
C   CHECK IF THERE IS ONLY ONE ACTIVE PATH AND IF SO SKIP
C   THE ITERATION
C
IF (NEXTPATH (OD).EQ.0) THEN
  NODE=DEST (OD)
  DO WHILE (NODE.NE.ORIGIN)

```

```

      ARC=PA (NODE)
      IF (ARC.NE.PRED (NODE,1,COMMODITY)) GO TO 180
      NODE=STARTNODE (ARC)
    END DO
    GO TO 500
  END IF

```

C
180
C
C
C

```

CONTINUE

      MARK THE ARCS OF THE SHORTEST PATH

```

```

    DESTOD=DEST (OD)
    NODE=DESTOD
    DO WHILE (NODE.NE.ORIGIN)
      ARC=PA (NODE)
      MEMBER (ARC) = .TRUE.
      NODE=STARTNODE (ARC)
    END DO

```

C
C
C

```

      GENERATE LIST OF ACTIVE PATHS FOR OD PAIR

```

```

    NUMLIST=1
    PATHLIST (1) =OD
    PATH=NEXTPATH (OD)
    DO WHILE (PATH.GT.0)
      NUMLIST=NUMLIST+1
      PATHLIST (NUMLIST) =PATH
      PATH=NEXTPATH (PATH)
    END DO

```

C
C
C
C
C

```

      DETERMINE 1ST & 2ND DERIVATIVE LENGTH OF ACTIVE PATHS
      ALSO DETERMINE WHETHER THE CALCULATED SHORTEST PATH
      IS ALREADY IN THE LIST

```

```

    SPNEW=.TRUE.
    DO 200 K=1,NUMLIST
      SAME=.TRUE.
      FDER=0
      SDER=0
      TMINSDER=0
      PATH=PATHLIST (K)
      ITER=PATHID (PATH)
      NODE=DESTOD
      DO WHILE (NODE.NE.ORIGIN)
        ARC=PRED (NODE,ITER,COMMODITY)
        CALL DERIVS (COMMODITY,FA (ARC) ,ARC,D1CAL,D2CAL)
        FDER=FDER+D1CAL
        IF (.NOT.MEMBER (ARC)) THEN
          SDER=SDER+D2CAL
          SAME=.FALSE.
        ELSE
          SDER=SDER-D2CAL
          TMINSDER=TMINSDER+D2CAL
        END IF
        NODE=STARTNODE (ARC)
      END DO
      IF (SAME) THEN
        SPNEW=.FALSE.
        SHORTEST=PATH
        FDLLENGTH (K) =FDER
      END IF
    END DO

```

200
C
C
C

```

      MINFDER=FDER
      MINSDER=TMINSDER
    ELSE
      FDLENGTH(K)=FDER
      SDLENGTH(K)=SDER
    END IF
CONTINUE

```

*** INSERT SHORTEST PATH IN PATH LIST IF IT IS NEW ***

```

IF (SPNEW) THEN
  NUMPATH=NUMPATH+1
  SHORTEST=NUMPATH
  PATHID (NUMPATH) =NUMITER
  NEXTPATH (PATHLIST (NUMLIST) ) =NUMPATH
  NEXTPATH (NUMPATH) =0
  MINFDER=0
  MINSDER=0
  NODE=DESTOD
  DO WHILE (NODE.NE.ORIGIN)
    ARC=PA (NODE)
    CALL DERIVS (COMMODITY,FA (ARC) ,ARC,D1CAL,D2CAL)
    MINFDER=MINFDER+D1CAL
    MINSDER=MINSDER+D2CAL
    NODE=STARTNODE (ARC)
  END DO
END IF

```

C
C
C

**** UPDATE PATH & LINK FLOWS ****

```

  INCR=0
  TEMPERROR=0
  DO 250 K=1,NUMLIST
    DLENGTH=FDLENGTH(K)-MINFDER
    IF (DLENGTH.GT.0) THEN
      PATH=PATHLIST(K)
      FLOW=FP(PATH)
    IF ((FLOW.EQ.0.0).AND.(K.GT.1)) THEN
      NEXTPATH(PATHLIST(K-1))=NEXTPATH(PATH)
      GO TO 250
    END IF
    PATHINCR=DLENGTH/(SDLENGTH(K)+MINSDER)
    IF (FLOW.LE.PATHINCR) THEN
      FP(PATH)=0.0
      PATHINCR=FLOW
    ELSE
      FP(PATH)=FLOW-PATHINCR
    END IF
    INCR=INCR+PATHINCR
    TEMPERROR=TEMPERROR+FLOW*DLENGTH/FDLENGTH(K)
    ITER=PATHID(PATH)
    NODE=DESTOD
    DO WHILE (NODE.NE.ORIGIN)
      ARC=PRED(NODE,ITER,COMMODITY)
      FA(ARC)=FA(ARC)-PATHINCR
      NODE=STARTNODE(ARC)
    END DO
  END IF
CONTINUE

```

250
C


```

C
C      *** UPDATE THE ERROR CRITERION ***
C
C      CURERROR=AMAX1 (CURERROR,TEMPERROR/INPUT_FLOW(OD))
C
C      **** UPDATE FLOWS FOR SHORTEST PATH ****
C
C      FP (SHORTEST)=FP (SHORTEST) +INCR
C      NODE=DESTOD
C      DO WHILE (NODE.NE.ORIGIN)
C          ARC=PA (NODE)
C          FA (ARC)=FA (ARC) +INCR
C          MEMBER (ARC)=.FALSE.
C          NODE=STARTNODE (ARC)
C      END DO
C
C      500      CONTINUE
C
C      ***** END OF LOOP FOR OD PAIRS CORRESPONDING TO COMMODITY
C      ***** UPDATE TOTAL DELAY
C
C      CALL DELAY (DTOT (NUMITER) )
C
C      1000     CONTINUE
C
C      CHECK IF THE # OF ACTIVE PATHS EXCEED THE ALLOCATED NUMBER
C
C      IF (NUMPATH.GT.NNUMPATH) THEN
C          WRITE (6,*) 'MAX # OF ALLOCATED PATHS EXCEEDED'
C          STOP
C      END IF
C
C      OUTPUT THE CURRENT SOLUTION TO DISK
C
C      CALL PRFLOW
C
C      ***** END OF ITERATION *****
C
C      *** IF THE ERROR IS SMALLER THAN TOL, OR THE LIMIT ON
C      THE NUMBER OF ITERATIONS IS REACHED RETURN
C      ELSE GO FOR ANOTHER ITERATION
C
C      IF ((CURERROR.LT.TOL) .OR. (NUMITER.EQ.MAXITER)) THEN
C          RETURN
C      ELSE
C          GO TO 110
C      END IF
C
C      END
C      ***** END OF MULTIFLO *****

```

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      SHORTHEAP
C      'SHORTHEAP' SOLVES THE SHORTEST PATH PROBLEM BY
C      DIJKSTRA'S ALGORITHM AND A HEAP DATA STRUCTURE.
C      THIS ALGORITHM SHOULD BE USED WHEN THE NUMBER OF
C      DESTINATIONS FOR EACH COMMODITY IS SMALL RELATIVE
C      TO THE TOTAL NUMBER OF NODES.
C
C      INPUT:
C      S - THE STARTING NODE
C      COMMODITY - THE CORRESPONDING COMMODITY
C
C      OUTPUT:
C      PA(I) - THE LAST ARC ON THE SHORTEST PATH ENDING AT NODE I
C      DIST(I) - THE SHORTEST DISTANCE TO NODE I
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      SUBROUTINE SP (S,COMMODITY)
C
C      IMPLICIT NONE
C
C      ***** INCLUDE COMMON BLOCKS *****
C
C      INCLUDE 'PARAM.DIM'
C      INCLUDE 'NETWRK.PRM'
C      INCLUDE 'PATHS.BLK'
C
C      ***** LOCAL VARIABLE DEFINITIONS *****
C
C      REAL      MIN
C                TEMPORARY MINIMUM VALUE
C      REAL      D1,D2,DP
C                NODE DISTANCE
C      REAL      XLARGE
C                BIG X BY DEFAULT
C      INTEGER   S
C                INPUT NODE
C      INTEGER   COMMODITY
C                INPUT COMMODITY
C      INTEGER   P
C                NODE ALONG THE PATH OF S TO DESTINATIONS
C      INTEGER   I
C                DO LOOP INDEX
C      INTEGER   J
C                DO LOOP INDEX
C      INTEGER   ARC
C                DO LOOP INDEX
C      INTEGER   ND
C                A NODE INDEX
C      INTEGER   DNUMBER
C                # OF DESTINATIONS FOR COMMODITY
C      INTEGER   N1
C                TEMPORARY VARIABLE
C      INTEGER   N2
C                TEMPORARY VARIABLE
C      INTEGER   UPNODE,DOWNNODE,DOWNNODE1,LASTNODE
C                VARIABLES USED IN UPDATING THE HEAP ARRAY
C      INTEGER   CURRANK,NEWRANK

```

```

C          VARIABLES USED IN UPDATING THE HEAP ARRAY
C          INTEGER ENDHEAP
C          MARKS THE LAST ELEMENT OF THE HEAP ARRAY
C          INTEGER RANK (NNN)
C          RANK (NODE) GIVES THE RANK OF NODE IN THE HEAP
C          INTEGER NRANK (NNN)
C          NRANK (I) GIVES THE NODE OF RANK I IN THE HEAP
C          REAL D1CAL
C          FIRST DERIVATIVE OF DELAY WITH RESPECT TO LOAD
C          LOGICAL FIRSTITER
C          TRUE IF THIS IS THE FIRST ITERATION
C          LOGICAL SCAN (NNN)
C          LOGICAL INDICATING THAT A NODE HAS BEEN SCANNED
C          LOGICAL DSTATUS (NNN)
C          LOGICAL SPECIFYING IF A NODE IS A DESTINATION
C
C          ***** EXECUTABLE CODE *****
C
C          XLARGE=1E15
C          D1CAL=1.0
C          P=S
C          DO 10 I=1,NN
C             DIST (I)=XLARGE
C             SCAN (I)=.FALSE.
C             DSTATUS (I)=.FALSE.
10          CONTINUE
C          DIST (S)=0
C          IF (NUMITER.EQ.1) THEN
C             FIRSTITER=.TRUE.
C          ELSE
C             FIRSTITER=.FALSE.
C          END IF
C
C          MARK THE DESTINATION NODES
C
C          N1=STARTOD (COMMODITY)
C          N2=STARTOD (COMMODITY+1) -1
C          DNUMBER=N2-N1+1
C          DO 15 I=N1,N2
C             DSTATUS (DEST (I))=.TRUE.
15          CONTINUE
C
C          INITIALIZE THE HEAP FLOOR
C
C          ENDHEAP=0
C
C          ***** SCAN NODE P *****
C
C          1000 CONTINUE
C             SCAN (P)=.TRUE.
C             IF (DSTATUS (P)) THEN
C                IF (DNUMBER.EQ.1) RETURN
C                DNUMBER=DNUMBER-1
C             END IF
C             IF (FRSTOU (P).NE.0) THEN
C                DP=DIST (P)
C                DO 20 ARC=FRSTOU (P),LASTOU (P)
C                   ND=ENDNODE (ARC)
C                   IF (.NOT.SCAN (ND)) THEN
C                      IF (.NOT.FIRSTITER) THEN

```

```

CALL DERIV1 (COMMODITY,FA (ARC) ,ARC,D1CAL)
END IF
D2=DIST (ND)
C IF ND HAS NOT BEEN LABELLED INSERT IT IN THE HEAP
IF (D2.EQ.XLARGE) THEN
ENDHEAP=ENDHEAP+1
RANK (ND) =ENDHEAP
NRANK (ENDHEAP) =ND
END IF
D1=DP+D1CAL
IF (D1.LT.D2) THEN
PA (ND) =ARC
DIST (ND) =D1
CURRANK=RANK (ND)
50 NEWRANK=INT (CURRANK/2)
IF (NEWRANK.GE.1) THEN
UPNODE=NRANK (NEWRANK)
IF (D1.LT.DIST (UPNODE)) THEN
NRANK (CURRANK) =UPNODE
RANK (UPNODE) =CURRANK
CURRANK=NEWRANK
GO TO 50
END IF
END IF
NRANK (CURRANK) =ND
RANK (ND) =CURRANK
END IF
END IF
20 CONTINUE
END IF
C
C ***** FIND NEXT NODE TO SCAN *****
C
C TEST FOR ERROR
IF (ENDHEAP.EQ.0) THEN
WRITE (6,*) 'ERROR IN THE SHORTEST PATH ROUTINE'
STOP
END IF
P=NRANK (1)
C
C RESTRUCTURE HEAP ARRAYS
C
LASTNODE=NRANK (ENDHEAP)
ENDHEAP=ENDHEAP-1
D1=DIST (LASTNODE)
CURRANK=1
100 NEWRANK=CURRANK+CURRANK
IF (NEWRANK.LE.ENDHEAP) THEN
DOWNNODE=NRANK (NEWRANK)
IF (NEWRANK.EQ.ENDHEAP) THEN
DOWNNODE1=DOWNNODE
ELSE
DOWNNODE1=NRANK (NEWRANK+1)
END IF
IF (DIST (DOWNNODE) .LE.DIST (DOWNNODE1)) THEN
IF (D1.GT.DIST (DOWNNODE)) THEN
NRANK (CURRANK) =DOWNNODE
RANK (DOWNNODE) =CURRANK
CURRANK=NEWRANK
GO TO 100

```

```
      END IF
    ELSE
      IF (D1.GT.DIST(DOWNNODE1)) THEN
        NRANK(CURRANK)=DOWNNODE1
        RANK(DOWNNODE1)=CURRANK
        CURRANK=NEWNRANK+1
        GO TO 100
      END IF
    END IF
    NRANK(CURRANK)=LASTNODE
    RANK(LASTNODE)=CURRANK
    GO TO 1000
  END
```

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C   SHORTPAPE
C   'SHORTPAPE' SOLVES THE SHORTEST PATH PROBLEM BY
C   PAPE'S MODIFICATION OF BELLMAN'S ALGORITHM.
C
C   INPUT:
C   S - THE STARTING NODE
C   COMMODITY - THE CORRESPONDING COMMODITY
C
C   OUTPUT:
C   PA(I) - THE LAST ARC ON THE SHORTEST PATH ENDING AT NODE I
C   DIST(I) - THE SHORTEST DISTANCE TO NODE I
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C   SUBROUTINE SP(S,COMMODITY)
C
C   IMPLICIT NONE
C
C   ***** INCLUDE COMMON BLOCKS *****
C
C   INCLUDE 'PARAM.DIM'
C   INCLUDE 'NETWRK.PRM'
C   INCLUDE 'PATHS.BLK'
C
C   ***** LOCAL VARIABLE DEFINITIONS *****
C
C   REAL    D1,DP
C           NODE DISTANCE
C   REAL    XLARGE
C           BIG X BY DEFAULT
C   INTEGER ILARGE
C           INTEGER LARGER THAN THE NUMBER OF NODES
C   INTEGER S
C           INPUT NODE
C   INTEGER COMMODITY
C           INPUT COMMODITY
C   INTEGER P
C           NODE PRESENTLY SCANNED
C   INTEGER I
C           DO LOOP INDEX
C   INTEGER ARC
C           DO LOOP INDEX
C   INTEGER ND
C           A NODE INDEX
C   INTEGER N1
C           TEMPORARY VARIABLE
C   INTEGER N2
C           TEMPORARY VARIABLE
C   INTEGER ENDQUEUE
C           MARKS THE LAST ELEMENT OF THE QUEUE ARRAY
C   REAL    D1CAL
C           FIRST DERIVATIVE OF DELAY WITH RESPECT TO FLOW
C   LOGICAL FIRSTITER
C           TRUE IF THIS IS THE FIRST ITERATION
C   INTEGER Q(NNN)
C           QUEUE OF NODES TO BE SCANNED
C
C   ***** EXECUTABLE CODE *****

```

```

C
XLARGE=1E15
ILARGE=NNN+1
D1CAL=1.0
DO 10 I=1,NN
    DIST(I)=XLARGE
    Q(I)=0
10 CONTINUE
IF (NUMITER.EQ.1) THEN
    FIRSTITER=.TRUE.
ELSE
    FIRSTITER=.FALSE.
END IF
DIST(S)=0
Q(S)=ILARGE
ENDQUEUE=S
P=S

C
C ***** START OF MAIN ALGORITHM *****
C
100 CONTINUE
C
C ***** SCAN NODE P *****
C
N1=FRSTOU(P)
IF (N1.EQ.0) GO TO 201
N2=LASTOU(P)
DP=DIST(P)
DO 200 ARC=N1,N2
    ND=ENDNODE(ARC)
    IF (.NOT.FIRSTITER) THEN
        CALL DERIV1(COMMODITY,FA(ARC),ARC,D1CAL)
    END IF
    D1=DP+D1CAL
C ***** IF NO IMPROVEMENT TAKE ANOTHER ARC *****
C IF (D1.GE.DIST(ND)) GO TO 200
C ***** CHANGE DISTANCE AND LABEL OF NODE ND *****
    PA(ND)=ARC
    DIST(ND)=D1
    IF (Q(ND)) 160,140,200
C ***** IF ND HAS NEVER BEEN SCANNED INSERT IT AT THE END
C OF THE QUEUE *****
140 Q(ENDQUEUE)=ND
    ENDQUEUE=ND
    Q(ND)=ILARGE
    GO TO 200
C ***** IF ND HAS ALREADY BEEN SCANNED ADD IT AT THE
C BEGINNING OF THE QUEUE AFTER NODE P *****
160 Q(ND)=Q(P)
    Q(P)=ND
    IF (ENDQUEUE.EQ.P) ENDQUEUE=ND
200 CONTINUE
C
C ***** GET NEXT NODE FROM THE TOP OF THE QUEUE *****
C
201 N1=Q(P)
C
C ***** FLAG P AS HAVING BEEN SCANNED *****
C
Q(P)=-1

```

P=N1

C
C
C
C

*** IF THE QUEUE IS NOT EMPTY GO BACK TO SCAN NEXT NODE ***

IF (P.LT.ILARGE) GO TO 100

RETURN
END


```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      DELAY
C
C      DELAY COMPUTES THE TOTAL M/M/1 DELAY IN ROUTING COMMODITIES FROM
C      SOURCES TO SINKS.
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
      SUBROUTINE DELAY(DT)
      IMPLICIT NONE
C
C      ***** INCLUDE COMMON BLOCKS *****
C
      INCLUDE 'PARAM.DIM'
      INCLUDE 'PATHS.BLK'
      INCLUDE 'NETWRK.PRM'
      INCLUDE 'CONVRG.PRM'
C
C      ***** ARGUMENT DEFINITIONS *****
C
      ON OUTPUT:
C
      REAL      DT
                TOTAL SYSTEM DELAY
C
C      ***** EXTERNAL FUNCTIONS REFERENCED *****
C
      REAL      DCAL
                DELAY AS A FUNCTION OF FLOW
C
C      ***** LOCAL VARIABLE DEFINITIONS *****
C
      INTEGER K
                DO LOOP INDEX
C
C      ***** EXECUTABLE CODE *****
C
      LOOP OVER ALL LINKS AND ACCRUE TOTAL DELAY
C
      DT=0.
      DO 50 K=1,NA
          DT=DT+DCAL (FA(K) ,K)
50      CONTINUE
C
      RETURN
      END

```



```

C
C ***** EXECUTABLE CODE *****
C
RATE=BITRATE (ARC)
MAXI=MAXUTI*RATE
EXCESS=X-MAXI
C
IF (EXCESS.LE.0.0) THEN
C
C     DERIVATIVES OF M/M/1 QUEUEING DELAY
C
C     T=RATE-X
C     D1CAL=RATE/T**2
C     D2CAL=2.0*D1CAL/T
ELSE
C
C     DERIVATIVES OF THE QUADRATIC APPROXIMATION
C
C     T=RATE-MAXI
C     D1=RATE/T**2
C     D2CAL=2.0*D1/T
C     D1CAL=D1+D2CAL*EXCESS
END IF
RETURN
END
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C     DERIV1
C
C     'DERIV1' COMPUTES THE FIRST DERIVATIVE OF DELAY WITH RESPECT
C     TO FLOW FOR LINKS.  BELOW A MAXIMUM UTILIZATION, M/M/1 DELAY IS
C     ASSUMED TO APPLY WHEREAS A QUADRATIC APPROXIMATION IS ASSUMED FOR
C     UTILIZATIONS BEYOND THE MAXIMUM.  THE DERIVATIVES ARE CONTINUOUS
C     AT THE MAXIMUM UTILIZATION.
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
SUBROUTINE DERIV1 (COMMODITY,X,ARC,D1CAL)
IMPLICIT NONE
C
C ***** INCLUDE COMMON BLOCKS *****
C
INCLUDE 'PARAM.DIM'
INCLUDE 'NETWRK.PRM'
INCLUDE 'CONVRG.PRM'
INCLUDE 'PATHS.BLK'
C
C ***** ARGUMENT DEFINITIONS *****
C
ON INPUT:
C
INTEGER COMMODITY
      THE CORRESPONDING COMMODITY
C
REAL X
      FLOW IN THE SPECIFIED LINK
C
INTEGER ARC
      THE SPECIFIED ARC
C
ON OUTPUT:

```

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      PRFLOW
C
C      'PRFLOW' OUTPUTS INTERMEDIATE RESULTS IN THE MULTIFLO ALGORITHM.
C      ITERATION #, DELAY, NUMBER OF ACTIVE PATHS GENERATED AND
C      CONVERGENCE ARE THE PRIMARY OUTPUTS.
C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
      SUBROUTINE PRFLOW
      IMPLICIT NONE
C
C      ***** INCLUDE COMMON BLOCKS *****
C
      INCLUDE 'PARAM.DIM'
      INCLUDE 'NETWRK.PRM'
      INCLUDE 'CONVRG.PRM'
      INCLUDE 'PATHS.BLK'
C
C      ***** LOCAL VARIABLE DEFINITIONS *****
C
      LOGICAL FIRFLG
      FIRST PASS FLAG FOR OUTPUT CONTROL
      INTEGER I
      DO LOOP INDEX
C
C      ***** LOCAL DATA INITIALIZATION *****
C
      DATA FIRFLG/.TRUE./
C
      ON THE VERY FIRST PASS, OUTPUT THE CONTENTS OF INPUT BLOCKS TO FILE
C
      IF (FIRFLG) THEN
        WRITE (6,*) '*****'
        WRITE (6,*) '*          MULTIFLO SUMMARY          *'
        WRITE (6,*) '*****'
        WRITE (6,*) ' '
        WRITE (6,*) '*****'
        WRITE (6,*) '*          INITIALIZATION DATA          *'
        WRITE (6,*) '*****'
        WRITE (6,*) ' '
        WRITE (6,*) 'NETWORK SPECIFICATION DATA:'
        WRITE (6,*) ' '
        WRITE (6,*) 'NODE SPECIFICATIONS'
        WRITE (6,*) 'NUMBER OF NODES:',NN
        WRITE (6,*) 'NODE #          FRSTOU          LASTOU'
        DO I=1,NN
          WRITE (6,*) I,FRSTOU(I),LASTOU(I)
        END DO
        WRITE (6,*) ' '
        WRITE (6,*) 'LINK SPECIFICATIONS:'
        WRITE (6,*) 'NUMBER OF LINKS:',NA
        WRITE (6,*) 'LINK #          STARTNODE          ENDNODE          BITRATE'
        DO I=1,NA
          WRITE (6,*) I,STARTNODE(I),ENDNODE(I),BITRATE(I)
        END DO
        WRITE (6,*) ' '
        WRITE (6,*) 'COMMODITY SPECIFICATIONS'
        WRITE (6,*) 'NUMBER OF COMMODITIES:',NUMCOMMOD
      END IF

```

```

WRITE (6,*) 'COMMOD #      ORGID      STARTOD'
DO I=1,NUMCOMMOD
  WRITE (6,*) I,ORGID(I),STARTOD(I)
END DO
WRITE (6,*) ' '
WRITE (6,*) 'OD PAIR SPECIFICATIONS'
WRITE (6,*) 'NUMBER OF OD PAIRS: ',NUMODPAIR
WRITE (6,*) 'OD PAIR #      DEST      INPUT FLOW'
DO I=1,NUMODPAIR
  WRITE (6,*) I,DEST(I),INPUT_FLOW(I)
END DO
WRITE (6,*) ' '
WRITE (6,*) '*****'
WRITE (6,*) '*      MULTIFLO DATA BY ITERATION      *'
WRITE (6,*) '*****'
WRITE (6,*) 'ITERATION #      TOTAL DELAY      CONVERGENCE      NUMBER OF'
WRITE (6,*) '      ERROR      ACTIVE'
WRITE (6,*) '      PATHS'
FIRFLG=.FALSE.
END IF
IF (NUMITER.GT.0) THEN
  WRITE (6,*) NUMITER,DTOT (NUMITER),CURError,NUMPATH
END IF
RETURN
END

```



```

C      'INCLUDE' FILE NETWRK.PRM
C
C      'NETWRK.PRM' CONTAINS THE NETWORK SPECIFICATION PARAMETERS
C
COMMON /NETWORK/
&      NN,FRSTOU, LASTOU,
&      NA, STARTNODE, ENDNODE, BITRATE,
&      NUMCOMMOD, ORGID, STARTOD,
&      NUMODPAIR, DEST, INPUT_FLOW
C
C      INTEGER*2      NN
C                        NUMBER OF NODES IN THE NETWORK
C      INTEGER*2      FRSTOU (NNN)
C                        THE FIRST ARC EMANATING FROM A NODE
C      INTEGER*2      LASTOU (NNN)
C                        THE FINAL ARC EMANATING FROM A NODE
C
C      INTEGER*2      NA
C                        NUMBER OF LINKS (ARCS) IN THE NETWORK
C      INTEGER*2      STARTNODE (NNA)
C                        THE START NODE FOR AN ARC
C      INTEGER*2      ENDNODE (NNA)
C                        THE END NODE FOR AN ARC
C      REAL           BITRATE (NNA)
C                        THE LINK CAPACITY IN BITS/SECOND
C
C      INTEGER*2      NUMCOMMOD
C                        THE NUMBER OF COMMODITIES IN THE NETWORK
C      INTEGER*2      ORGID (NNORIG)
C                        THE NODE NUMBER OF THE ORIGIN
C      INTEGER*2      STARTOD (NNORIG)
C                        THE POINTER TO THE STARTING NODE IN AN OD PAIR
C
C      INTEGER*2      NUMODPAIR
C                        THE NUMBER OF OD PAIRS
C      INTEGER*2      DEST (NNUMOD)
C                        THE DESTINATION NODE OF TRAFFIC IN AN OD PAIR
C      REAL           INPUT_FLOW (NNUMOD)
C                        THE INPUT TRAFFIC TO THE NODE IN BITS/SECOND
C

```



```
C      'INCLUDE' FILE CONVRG.PRM
C
C      'CONVRG.PRM' CONTAINS THE CONVERGENCE PARAMETERS FOR THE
C      NETWORK FLOW PROBLEM
C
C      COMMON /CONVRG/
C      &          MAXITER,TOL,MAXUTI,OUTPFL
C
C      INTEGER MAXITER
C          MAXIMUM NUMBER OF ITERATIONS IN THE SOLUTION
C      REAL    TOL
C          TOLERANCE ON SOLUTION ACCURACY
C      REAL    MAXUTI
C          MAXIMUM UTILIZATION FOR M/M/1 QUEUE DELAY
C      LOGICAL OUTPFL
C          OUTPUT CONTROL VARIABLE
```

```

C      'INCLUDE' FILE PATHS.BLK
C
C      'PATHS.BLK' DEFINES THE ARRAYS NECESSARY TO MAINTAIN
C      PATH FLOWS AND DESCRIPTION.
C
COMMON /PATHS/
&      PA,FA,PATHID,NEXTPATH,FP,DIST,DTOT,CURERROR,
&      NUMPATH,NUMITER
C
C      INTEGER*2      PA (NNN)
C                      THE LAST ARC ON A SHORTEST PATH TO A NODE
C      REAL          FA (NNA)
C                      THE FLOW IN ANY GIVEN LINK (ARC)
C      INTEGER       PATHID (NNUMPATH)
C                      THE PATH IDENTIFIER FOR ANY GIVEN PATH
C      INTEGER       NEXTPATH (NNUMPATH)
C                      THE NEXT PATH FOR THE SAME OD PAIR
C      REAL          FP (NNUMPATH)
C                      THE FLOW OF A PATH
C      REAL          DIST (NNN)
C                      SHORTEST DISTANCE TO A NODE FROM THE ORIGIN
C      REAL          DTOT (NMAXITER)
C                      THE TOTAL DELAY BY ITERATION
C      INTEGER       NUMITER
C                      CURRENT ITERATION NUMBER
C      REAL          CURERROR
C                      CONVERGENCE ERROR (NORMALISED % OF FLOW NOT ON
C                      A SHORTEST PATH)
C      INTEGER       NUMPATH
C                      NUMBER OF GENERATED PATHS

```

CC

C
C SETUP

C 'SETUP' ACCEPTS INPUTS FROM THE TERMINAL AND CREATES DATA SETS
C THAT REPRESENTS NETWORKS AND LOADS IN A FORM SUITABLE FOR
C PROGRAM 'MULTIFLO'

CC

C
C PROGRAM SETUP
C IMPLICIT NONE

C
C ***** INCLUDE COMMON BLOCKS *****

C INCLUDE 'PARAM.DIM'
C INCLUDE 'NETWRK.PRM'

C
C ***** LOCAL VARIABLE DEFINITIONS *****

C INTEGER TERMINAL_NODE
C THE END NODE OF A LINK
C INTEGER DESTOD
C THE DESTINATION NODE OF AN OD PAIR
C REAL BPS
C MAXIMUM LINK CAPACITY
C INTEGER NUMARC
C NUMBER OF OUTGOING ARCS FOR A NODE IN THE NETWORK
C REAL TRAFFIC
C SPECIFIED INPUT TO AN OD PAIR
C INTEGER I
C DO LOOP INDEX
C INTEGER J
C DO LOOP INDEX
C INTEGER NOD
C NUMBER OF OD PAIRS ASSOCIATED WITH A COMMODITY

C ***** EXECUTABLE CODE *****

C GET THE NODE SPECIFICATIONS

C NA=0
C WRITE(6,*) 'INPUT THE # OF NODES'
C READ(5,*) NN
C DO I=1, NN
200 WRITE(6,*) 'FOR NODE', I, ' ENTER # OF ARCS EXITING THE NODE'
C READ(5,*,ERR=200) NUMARC
C IF (NUMARC.GE.0) THEN
100 DO J=1, NUMARC
C WRITE(6,*) 'FOR ARC', J, ' AT NODE', I, ' ENTER TERMINAL NODE',
C & ' AND MAXIMUM BITS/S'
C ASK THE SAME QUESTION ON ERRORS
C READ(5,*,ERR=100) TERMINAL_NODE, BPS
C IF (TERMINAL_NODE.GT.NN) THEN
C WRITE(6,*) 'TERMINAL NODE OUT OF BOUNDS'
C GO TO 100
C ELSE

C

C
C

ENTER LINK BEGIN AND END NODES

```

      NA=NA+1
      ENDNODE (NA) =TERMINAL_NODE
      BITRATE (NA) =BPS
    END IF
    STARTNODE (NA) =I
  END DO
  FRSTOU (I) =NA-NUMARC+1
  LASTOU (I) =NA
ELSE
  WRITE (6,*) 'NEGATIVE ARCS ILLEGAL'
  GO TO 200
END IF
END DO

```

C
C
C

OD PAIRS SETUP

1000

```

WRITE (6,*) 'ENTER THE NUMBER OF COMMODITIES IN THE NETWORK'
READ (5,*,ERR=1000) NUMCOMMOD
NUMODPAIR=0
DO I=1,NUMCOMMOD

```

300

```

  WRITE (6,*) 'ENTER THE ORIGIN ID AND NUMBER OF DESTINATIONS FOR ',
    & 'COMMODITY',I

```

```

  READ (5,*,ERR=300) ORGID (I) ,NOD
  IF (ORGID (I) .LE .NN) THEN

```

400

```

    DO J=1,NOD
      WRITE (6,*) 'ENTER THE DESTINATION',J,' AND TRAFFIC FOR ',
        & 'COMMODITY'

```

C
C
C

ASK THE SAME QUESTION ON ERRORS

```

  READ (5,*,ERR=400) DESTOD,TRAFFIC
  IF (DESTOD.GT.NN) THEN
    WRITE (6,*) 'DESTINATION OD OUT OF BOUNDS, MAXIMUM=',NN
    GO TO 400
  ELSE

```

```

    NUMODPAIR=NUMODPAIR+1
    DEST (NUMODPAIR) =DESTOD
    INPUT_FLOW (NUMODPAIR) =TRAFFIC
  END IF

```

```

  END DO
ELSE
  WRITE (6,*) 'ORIGIN IS OUT OF BOUNDS, MAX ORIGIN=',NN
  GO TO 300
END IF

```

```

  STARTOD (I) =NUMODPAIR-NOD+1
END DO

```

C
C
C
C

OUTPUT OF CONNECTIVITY DATA FOR DIRECT INPUT INTO 'MULTIFLO'
COMMON BLOCKS

```

WRITE (1,*) NN
DO I=1,NN
  WRITE (1,*) FRSTOU (I) ,LASTOU (I)
END DO
WRITE (1,*) NA
DO I=1,NA
  WRITE (1,*) STARTNODE (I) ,ENDNODE (I) ,BITRATE (I)
END DO

```

C
C
C
C

OUTPUT OF OD TRAFFIC DATA FOR DIRECT INPUT INTO 'MULTIFLO'
COMMON BLOCKS

```
WRITE (2,*) NUMCOMMOD
DO I=1, NUMCOMMOD
  WRITE (2,*) ORGID (I) , STARTOD (I)
END DO
WRITE (2,*) NUMODPAIR
DO I=1, NUMODPAIR
  WRITE (2,*) DEST (I) , INPUT_FLOW (I)
END DO
STOP
END
```

APPENDIX II: MULTIFLO1 Code

The only differences between MULTIFLO and MULTIFLO1 are in the DRIVER program and in the main algorithm subroutine MULTIFLO. These two routines called DRIVER1 and MULTIFLO1, are listed below.

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C   DRIVER1
C
C   'DRIVER1' IS A SIMPLE EXECUTIVE TO INVOKE THE 'MULTIFLO1' COMMODITY
C   ROUTING PROGRAM. 'DRIVER1' INVOKES SUBPROGRAM 'LOAD' TO READ
C   DATA INTO 'MULTIFLO1' INPUT COMMON BLOCKS. FILES READ BY
C   'LOAD' ARE CREATED BY A TERMINAL SESSION WITH THE USER FOR
C   NETWORK DEFINITION THROUGH THE USE OF PROGRAM 'SETUP'.
C
C   EXECUTION STEPS FOR PROGRAM 'DRIVER1'
C
C       1) ASSIGN FORTRAN UNIT 01 AS CREATED BY PROGRAM 'LOAD'
C       2) ASSIGN FORTRAN UNIT 02 AS CREATED BY PROGRAM 'LOAD'
C       3) ASSIGN FORTRAN UNIT 06 AS A DESIGNATED OUTPUT FILE
C
C       E.G.:
C           $ ASSIGN NETWORK.DAT FOR001
C           $ ASSIGN TRAFFIC.DAT FOR002
C           $ ASSIGN OUTPUT.DAT FOR006
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C   PROGRAM DRIVER1
C
C   LOAD FORTRAN UNIT 01 AND FORTRAN UNIT 02 FROM DISK AS CREATED
C   FROM PROGRAM 'SETUP'
C
C   INCLUDE 'PARAM.DIM'
C   INCLUDE 'PATHS.BLK'
C   INCLUDE 'NETWRK.PRM'
C   INCLUDE 'CONVRG.PRM'
C   INTEGER COMMODITY,ORIGIN,DESTOD,OD,PATH
C   CALL LOAD
C
C   EXECUTE THE 'MULTIFLO1' NETWORK ALGORITHM. 'MULTIFLO1' SCHEDULES
C   ITS OWN OUTPUTS TO FORTRAN UNIT 06 ON EACH ITERATION
C
C   INITIALIZE THE TIMER
C   CALL LIB$INIT_TIMER
C   CALL MULTIFLO1
C   RECORD THE COMPUTATION TIME
C   CALL LIB$SHOW_TIMER
C
C       PRINT MAX LINK UTILIZATION (RELEVANT FOR M/M/1 QUEUEING DELAY
C       OPTIMIZATION)
C
C       UMAX=0.0
C       DO 100 I=1,NA
C           UMAX=MAX(UMAX,FA(I)/BITRATE(I))
100   CONTINUE
C       WRITE(6,*) 'MAXIMUM LINK UTILIZATION'
C       WRITE(6,*) UMAX
C
C   PRINT FINAL PATH FLOW INFO
C
C   WRITE(6,*) 'ORIGIN / DESTINATION / PATH # / PATH FLOW'
C   DO 1000 COMMODITY=1,NUMCOMM
C       ORIGIN=ORGID(COMMODITY)
C       DO 500 OD=STARTOD(COMMODITY),STARTOD(COMMODITY+1)-1

```

```
DESTOD=DEST (OD)
PATH=OD
DO WHILE (PATH.GT.0)
  WRITE (6, *) ORIGIN, DESTOD, PATH, FP (PATH)
  PATH=NEXTPATH (PATH)
END DO
500 CONTINUE
1000 CONTINUE
STOP
END
```


CC
C
C MULTIFLO1
C
C MULTICOMMODITY FLOW ALGORITHM BASED ON A PATH FLOW FORMULATION
C UPDATES THE PATH FLOWS OF OD PAIRS ONE AT A TIME ACCORDING TO
C AN ITERATION OF THE PROJECTION TYPE.
C
C DEVELOPED BY DIMITRI BERTSEKAS, BOB GENDRON, AND WEI K TSAI
C
C BASED ON THE PAPERS:
C
C 1) BERTSEKAS,D.P., "A CLASS OF OPTIMAL ROUTING ALGORITHMS
C FOR COMMUNICATION NETWORKS", PROC. OF 5TH ITERNATIONAL
C CONFERENCE ON COMPUTER COMMUNICATION (ICCC-80),
C ATLANTA, GA., OCT. 1980, PP.71-76.
C
C 2) BERTSEKAS,D.P. AND GAFNI,E.M., "PROJECTION METHODS
C FOR VARIATIONAL INEQUALITIES WITH APPLICATION TO
C THE TRAFFIC ASSIGNMENT PROBLEM", MATH. PROGR. STUDY,17,
C D.C.SORENSEN AND J.-B. WETS (EDS), NORTH-HOLLAND,
C AMSTERDAM,1982, PP. 139-159.
C
C 3) BERTSEKAS,D.P., "OPTIMAL ROUTING AND FLOW CONTROL
C METHODS FOR COMMUNICATION NETWORKS", IN ANALYSIS AND
C OPTIMIZATION OF SYSTEMS, (PROC. OF 5TH INTERNATIONAL
C CONFERENCE ON ANALYSIS AND OPTIMIZATION, VERSAILLES,
C FRANCE), A. BENSOUSSAN AND J.L. LIONS (EDS),
C SPRINGER-VERLAG, BERLIN & NY,1982, PP. 615-643.
C
C 4) BERTSEKAS,D.P. AND GAFNI, E.M., "PROJECTED NEWTON
C METHODS AND OPTIMIZATION OF MULTICOMMODITY FLOWS",
C IEEE TRANSACTIONS ON AUTOMATIC CONTROL, DEC. 1983.
C
C
C CCC

C SUBROUTINE MULTIFLO1

C IMPLICIT NONE

C ***** INCLUDE COMMON BLOCKS *****

- C INCLUDE 'PARAM.DIM'
- C INCLUDE 'NETWRK.PRM'
- C INCLUDE 'CONVRG.PRM'
- C INCLUDE 'PATHS.BLK'

C NODE ARRAYS (LENGTH NN):

- C FRSTOU(NODE) - FIRST ARC OUT OF NODE
- C LASTOU(NODE) - LAST ARC OUT OF NODE
- C NOTE: THE ARC LIST MUST BE ORDERED IN SEQUENCE SO
C THAT ALL ARCS OUT OF ANY NODE ARE GROUPED TOGETHER

C ARC ARRAYS (LENGTH NA):

- C FA(ARC) - THE TOTAL FLOW OF ARC
 - C STARTNODE(ARC) - THE HEAD NODE OF ARC
 - C ENDNODE(ARC) - THE TAIL NODE OF ARC
- C


```

REAL      INCR
C          TOTAL SHIFT OF FLOW TO THE MINIMUM FIRST DERIVATIVE LENGTH PATH
REAL      PATHINCR
C          SHIFT OF FLOW FOR A GIVEN PATH
REAL      FLOW
C          FLOW FOR A PATH
REAL      FDER
C          THE ACCRUED LENGTH ALONG A PATH
REAL      SDER
C          THE ACCRUED SECOND DERIVATIVE LENGTH ALONG A PATH
REAL      TEMPERROR
C          TEMPORARY STORAGE FOR CONVERGENCE ERROR
REAL      FDLLENGTH(NMAXITER)
C          ARRAY OF LENGTHS OF PATHS FOR AN OD PAIR
REAL      SDLENGTH(NMAXITER)
C          ARRAY OF SECOND DERIVATIVE LENGTHS OF PATHS FOR AN OD PAIR
INTEGER   PATHLIST(NMAXITER)
C          ARRAY OF ACTIVE PATHS FOR AN OD PAIR
INTEGER   COMMODITY
C          DO LOOP INDEX FOR THE OD PAIR ORIGINS
INTEGER   ORIGIN
C          SPECIFIC ORIGIN
INTEGER   I
C          DO LOOP INDEX
INTEGER   OD
C          OD DO LOOP INDEX
INTEGER   K
C          DO LOOP INDEX
INTEGER   SHORTEST
C          THE SHORTEST PATH
INTEGER   INDEX
C          THE CURRENT LAST ELEMENT OF THE ARRAY PDESCR
INTEGER   POINT
C          POINTER TO PDESCR
INTEGER   NUMARC
C          # OF ARCS IN A PATH
LOGICAL   MEMBER(NNA)
C          LOGICAL FOR AN ARC INCLUDED IN THE SHORTEST PATH
REAL      DLENGTH
C          DIFFERENCE IN PATH LENGTHS FOR THE TRAFFIC
REAL      D1CAL
C          ARC LENGTH
REAL      D2CAL
C          DERIVATIVE OF ARC LENGTH
C
C          ***** EXECUTABLE CODE *****
C
C          *****
C          *   INITIALIZATION
C          *****
C
DO 5 ARC=1,NA
  FA(ARC)=0.0
5 CONTINUE

DO I=1,NUMODPAIR
  FP(I)=INPUT_FLOW(I)
ENDDO
STARTOD(NUMCOMMOD+1)=NUMODPAIR+1
NUMPATH=0

```

```

INDEX=0
NUMITER=1
DO 100 COMMODITY=1,NUMCOMMOD
  ORIGIN=ORGID (COMMODITY)
  CALL SP (ORIGIN,COMMODITY)
C
C      LOOP OVER OD PAIRS OF COMMODITY
C
N1=STARTOD (COMMODITY)
N2=STARTOD (COMMODITY+1) -1
DO 50 OD=N1,N2
  NUMPATH=NUMPATH+1
  NEXTPATH (NUMPATH) =0
  FLOW=FP (NUMPATH)
  INDEX=INDEX+1
  NUMARC=0
  NODE=DEST (OD)
  DO WHILE (NODE.NE.ORIGIN)
    ARC=PA (NODE)
    FA (ARC) =FA (ARC) +FLOW
    PDESCR (INDEX) =ARC
    NUMARC=NUMARC+1
    INDEX=INDEX+1
    NODE=STARTNODE (ARC)
  END DO
  PATHID (NUMPATH) =INDEX
  PDESCR (INDEX) =NUMARC
50      CONTINUE
100     CONTINUE
C
C      INITIALIZE MEMBER ARRAY
C
DO 70 ARC=1,NA
  MEMBER (ARC) =.FALSE.
70     CONTINUE
C
C      INITIALIZE THE TOTAL DELAY
C
CALL DELAY (DTOT (NUMITER) )
C
C      OUTPUT THE CURRENT INFORMATION TO DISK
C
CALL PRFLOW
C
C      *****
C      *   END OF INITIALIZATION
C      *****
C
C      ***** START NEW ITERATION *****
C
110    NUMITER=NUMITER+1
      CURERROR=0
C
C      ***** LOOP OVER ALL COMMODITIES *****
C
DO 1000 COMMODITY=1,NUMCOMMOD
  ORIGIN=ORGID (COMMODITY)
  CALL SP (ORIGIN,COMMODITY)
C
C      ***** LOOP OVER OD PAIRS OF COMMODITY

```

C

```

N1=STARTOD (COMMODITY)
N2=STARTOD (COMMODITY+1) -1
DO 500 OD=N1,N2

```

C

C

C

C

```

CHECK IF THERE IS ONLY ONE ACTIVE PATH AND IF SO SKIP
THE ITERATION

```

```

IF (NEXTPATH(OD).EQ.0) THEN
  NODE=DEST(OD)
  POINT=PATHID(OD)
  NUMARC=PDESCR(POINT)
  DO 150 I=POINT-NUMARC,POINT-1
    ARC=PDESCR(I)
    IF (ARC.NE.PA(NODE)) GO TO 180
    NODE=STARTNODE(ARC)
  150 CONTINUE
  GO TO 500
END IF

```

150

C

180

C

C

C

```

CONTINUE

MARK THE ARCS OF THE SHORTEST PATH

```

```

DESTOD=DEST(OD)
NODE=DESTOD
DO WHILE (NODE.NE.ORIGIN)
  ARC=PA(NODE)
  MEMBER(ARC)=.TRUE.
  NODE=STARTNODE(ARC)
END DO

```

C

C

C

C

```

GENERATE LIST OF ACTIVE PATHS FOR OD PAIR

```

```

NUMLIST=1
PATHLIST(1)=OD
PATH=NEXTPATH(OD)
DO WHILE (PATH.GT.0)
  NUMLIST=NUMLIST+1
  PATHLIST(NUMLIST)=PATH
  PATH=NEXTPATH(PATH)
END DO

```

C

C

C

C

C

```

DETERMINE 1ST & 2ND DERIVATIVE LENGTH OF ACTIVE PATHS
ALSO DETERMINE WHETHER THE CALCULATED SHORTEST PATH
IS ALREADY IN THE LIST

```

```

SPNEW=.TRUE.
DO 200 K=1,NUMLIST
  SAME=.TRUE.
  FDER=0
  SDER=0
  TMINSDER=0
  PATH=PATHLIST(K)
  POINT=PATHID(PATH)
  NUMARC=PDESCR(POINT)
  DO 210 I=POINT-NUMARC,POINT-1
    ARC=PDESCR(I)
    CALL DERIVS (COMMODITY,FA(ARC),ARC,D1CAL,D2CAL)
  210
200

```

```

                FDER=FDER+D1CAL
                IF (.NOT.MEMBER (ARC)) THEN
                    SDER=SDER+D2CAL
                    SAME=.FALSE.
                ELSE
                    SDER=SDER-D2CAL
                    TMINSDER=TMINSDER+D2CAL
                END IF
210 CONTINUE
            IF (SAME) THEN
                SPNEW=.FALSE.
                SHORTEST=PATH
                FDLENGTH(K)=FDER
                MINFDER=FDER
                MINSDER=TMINSDER
            ELSE
                FDLENGTH(K)=FDER
                SDLENGTH(K)=SDER
            END IF
200 CONTINUE
C
C
C
*** INSERT SHORTEST PATH IN PATH LIST IF IT IS NEW ***

IF (SPNEW) THEN
    NUMPATH=NUMPATH+1
    SHORTEST=NUMPATH
    NEXTPATH (PATHLIST (NUMLIST)) =NUMPATH
    NEXTPATH (NUMPATH) =0
    MINFDER=0
    MINSDER=0
    INDEX=INDEX+1
    NUMARC=0
    NODE=DESTOD
    DO WHILE (NODE.NE.ORIGIN)
        ARC=PA (NODE)
        PDESCR (INDEX) =ARC
        NUMARC=NUMARC+1
        INDEX=INDEX+1
        CALL DERIVS (COMMODITY,FA (ARC) ,ARC,D1CAL,D2CAL)
        MINFDER=MINFDER+D1CAL
        MINSDER=MINSDER+D2CAL
        NODE=STARTNODE (ARC)
    END DO
    PATHID (NUMPATH) =INDEX
    PDESCR (INDEX) =NUMARC
END IF
C
C
C
**** UPDATE PATH & LINK FLOWS ****

    INCR=0
    TEMPERROR=0
    DO 250 K=1,NUMLIST
        DLENGTH=FDLENGTH(K)-MINFDER
        IF (DLENGTH.GT.0) THEN
            PATH=PATHLIST (K)
            FLOW=FP (PATH)
        IF ((FLOW.EQ.0.0).AND.(K.GT.1)) THEN
            NEXTPATH (PATHLIST (K-1)) =NEXTPATH (PATH)
            GO TO 250
        END IF

```

```

PATHINCR=DLENGTH/ (SDLENGTH (K) +MINSDER)
IF (FLOW.LE.PATHINCR) THEN
  FP (PATH)=0.0
  PATHINCR=FLOW
ELSE
  FP (PATH)=FLOW-PATHINCR
END IF
INCR=INCR+PATHINCR
TEMPERROR=TEMPERROR+FLOW*DLENGTH/FDLENGTH (K)
  POINT=PATHID (PATH)
  NUMARC=PDESCR (POINT)
  DO 220 I=POINT-NUMARC,POINT-1
    ARC=PDESCR (I)
    FA (ARC)=FA (ARC) -PATHINCR
220    CONTINUE
  END IF
250  CONTINUE
C
C
C    *** UPDATE THE ERROR CRITERION ***
C
C    CURERROR=AMAX1 (CURERROR,TEMPERROR/INPUT_FLOW (OD))
C
C
C    **** UPDATE FLOWS FOR SHORTEST PATH ****
C
C    FP (SHORTEST)=FP (SHORTEST) +INCR
C    POINT=PATHID (SHORTEST)
C    NUMARC=PDESCR (POINT)
C    DO 300 I=POINT-NUMARC,POINT-1
C      ARC=PDESCR (I)
C      FA (ARC)=FA (ARC) +INCR
C      MEMBER (ARC)=.FALSE.
300    CONTINUE
C
C
C    500  CONTINUE
C
C    ***** END OF LOOP FOR OD PAIRS CORRESPONDING TO COMMODITY
C    ***** UPDATE TOTAL DELAY
C
C    CALL DELAY (DTOT (NUMITER))
C
C
C    1000 CONTINUE
C
C    CHECK IF THE # OF ACTIVE PATHS EXCEED THE ALLOCATED NUMBER
C
C    IF (NUMPATH.GT.NNUMPATH) THEN
C      WRITE (6,*) 'MAX # OF ALLOCATED PATHS EXCEEDED'
C      STOP
C    END IF
C    IF (INDEX.GT.NINDEX) THEN
C      WRITE (6,*) 'DIMENSION OF PDESCR ARRAY EXCEEDED'
C      STOP
C    END IF
C
C
C    OUTPUT THE CURRENT SOLUTION TO DISK
C
C    CALL PRFLOW
C
C    ***** END OF ITERATION *****

```

```
C      *** IF THE ERROR IS SMALLER THAN TOL, OR THE LIMIT ON
C      THE NUMBER OF ITERATIONS IS REACHED RETURN
C      ELSE GO FOR ANOTHER ITERATION
C
      IF ((CURERROR.LT.TOL) .OR. (NUMITER.EQ.MAXITER)) THEN
          WRITE (6,*) 'FINAL STORAGE OF PATH DESCRIPTION LIST'
          WRITE (6,*) INDEX
          RETURN
      ELSE
          GO TO 110
      END IF
C
      END
C ***** END OF MULTIFLO1 *****
```